# Quasi-rational solutions of the NLS equation and rogue waves <br> Pierre Gaillard 

## To cite this version:

Pierre Gaillard. Quasi-rational solutions of the NLS equation and rogue waves. 2010. halshs00536287v2

## HAL Id: halshs-00536287 <br> https://shs.hal.science/halshs-00536287v2

Preprint submitted on 26 Nov 2010 (v2), last revised 16 Sep 2012 (v6)

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers.

L'archive ouverte pluridisciplinaire HAL, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

# Quasi-rational solutions of the NLS equation and rogue waves 

${ }^{+}$Pierre Gaillard, ${ }^{+}$Université de Bourgogne, Dijon, France :<br>e-mail: Pierre.Gaillard@u-bourgogne.fr,

November 4, 2010


#### Abstract

We degenerate solutions of the NLS equation from the general formulation in terms of theta functions given in [19], to get quasi-rational solutions of NLS equations. For this we establish a link between Fredholm determinants and wronskians. We give solutions of the NLS equation as a quotient of two wronskian determinants. In the limit when some parameter goes to 0 , we recover Peregrine's solution [32], and also Akhmediev's solutions given recently $[1,2,3,4,5,6,8]$. It gives a new approach to get the well known rogue waves.


## 1 Introduction

The nonlinear Schrödinger equation (NLS) equation plays a fundamental role in hydrodynamics, in particular for waves in deep water in the context of the rogue waves or in non-linear optics.
In this paper, we will study solutions of NLS equation from the theta formulation given by A. Its [19] and give a new representation in terms of wronskians. The solutions take the form of a quotient of two wronskians of elementary functions depending on a certain number of parameters.
If we take wronskians of order 2 N , we will call these solutions, solutions of NLS of order N .
Then, we take the limit when some parameter goes to 0 to get quasi-rational solutions of NLS equation.
At order 1, we recover the well known Peregrine's solution to the focusing

NLS equation which was first found [32] in 1983; it was rediscovered later in several publications, in particular [7].
The second order Peregrine-like solution was first constructed in [7]. Other Peregrine-like solutions were found for reduced Maxwell-Bloch integrable system [25, 26]. In [19], the n-phase quasi-periodic modulations of the plane waves solutions were constructed via appropriate degeneration of the finite gap periodic solutions to the NLS equation. These results have provided a way to construct multi-parametric families of multi-Peregrine solutions.
Interesting families of higher order were constructed using Darboux transformations in a series of articles be Akhmediev et al. [1, 2, 3, 4, 5, 6, 8].
Rational solutions of NLS equation are given in [31] in a determinantal representation as degenerate solutions of Davey-Stewartson equations. Another approach using Crum transformation is given in [18] to get sequences of rational solutions of NLS equation. Very recently, it is shown in [12] that rational solutions can be written as a quotient of two wronskians using modified version of [13], with some different reasoning; morever, the link between quasi-rational solutions to the focusing NLS equation and the rational solution of the KP-I equation is established.
Here, we give an another representation in terms of wronskians with simple generating functions, using central ideas of A . Its from finite gaps solutions in terms of theta functions.
With this formulation we recover as particular case,Akhmediev's quasi-rational solutions of NLS equation.

## 2 Expression of solutions of NLS equation in terms of Fredholm determinant

### 2.1 Solutions of NLS equation in terms of $\theta$ functions

The solution of the NLS equation

$$
\begin{equation*}
i v_{t}+v_{x x}+2|v|^{2} v=0, \tag{1}
\end{equation*}
$$

is given in terms of theta function by (see [19])

$$
\begin{equation*}
v(x, t)=\frac{\theta_{3}(x, t)}{\theta_{1}(x, t)} \exp (2 i t-i \varphi), \tag{2}
\end{equation*}
$$

where

$$
\begin{gather*}
\theta_{r}(x, t)=\sum_{k \in\{0 ; 1\}^{2 N}} \exp \left\{\sum_{\mu>\nu, \mu, \nu=1}^{2 N} \ln \left(\frac{\gamma_{\nu}-\gamma_{\mu}}{\gamma_{\nu}+\gamma_{\mu}}\right)^{2} k_{\mu} k_{\nu}\right.  \tag{3}\\
\left.+\left(\sum_{\nu=1}^{2 N} i \kappa_{\nu}\left(x-x_{0 \nu}\right)-2 \delta_{\nu}\left(t-t_{0 \nu}\right)+(r-1) \ln \frac{\gamma_{\nu}-i}{\gamma_{\nu}+i}+\sum_{\mu=1, \mu \neq \nu}^{2 N} \ln \left|\frac{\gamma_{\nu}+\gamma_{\mu}}{\gamma_{\nu}-\gamma_{\mu}}\right|+\pi i \epsilon_{\nu}\right) k_{\nu}\right\}, \quad r=1,3 .
\end{gather*}
$$

In this formula, the quantities $\kappa_{\nu}, \delta_{\nu}, \gamma_{\nu}$ are functions of the parameters $\lambda_{\nu}$, $\nu=1, \ldots, 2 N, N$ being a positive integer, $N \geq 1$ and they are given by the following equations,

$$
\begin{equation*}
\kappa_{\nu}=2 \sqrt{1-\lambda_{\nu}^{2}}, \quad \delta_{\nu}=\kappa_{\nu} \lambda_{\nu}, \quad \gamma_{\nu}=\sqrt{\frac{1-\lambda_{\nu}}{1+\lambda_{\nu}}}, \quad \epsilon_{\nu} \in\{0 ; 1\} \tag{4}
\end{equation*}
$$

$\varphi, x_{0 \nu}, t_{0 \nu}, \lambda_{\nu}$, and $\kappa_{\nu}, \delta_{\nu}, \gamma_{\nu}, \nu=1 \ldots 2 N$ are real numbers satisfying the conditions

$$
\begin{array}{lll}
x_{0 N+j}=x_{0 j}, & t_{0 N+j}=t_{0 j}, & 0<\lambda_{j}<1, \\
\lambda_{N+j}=-\lambda_{j}, & \kappa_{N+j}=\kappa_{j}, & \delta_{N+j}=-\delta_{j},
\end{array} \gamma_{N+j}=1 / \gamma_{j}, \quad j=1 \ldots N .
$$

### 2.2 Relation between $\theta$ and Fredholm determinant

The function $\theta_{r}$ defined in (3) can be rewritten with a summation in terms of subsets of $[1, . ., 2 N]$

$$
\begin{aligned}
& \theta_{r}(x, t)=\sum_{J \subset\{1, ., 2 N\}} \prod_{\nu \in J}(-1)^{\epsilon_{\nu}} \prod_{\nu \in J, \mu \notin J}\left|\frac{\gamma_{\nu}+\gamma_{\mu}}{\gamma_{\nu}-\gamma_{\mu}}\right| \\
& \times \exp \left\{\sum_{\nu \in J} i \kappa_{\nu}\left(x-x_{0 \nu}\right)-2 \delta_{\nu}\left(t-t_{0 \nu}\right)+x_{r, \nu}\right\},
\end{aligned}
$$

with

$$
\begin{equation*}
x_{r, \nu}=(r-1) \ln \frac{\gamma_{\nu}-i}{\gamma_{\nu}+i}, \quad 1 \leq j \leq 2 N \tag{5}
\end{equation*}
$$

in particular

$$
\begin{align*}
x_{r, j}=(r-1) \ln \frac{\gamma_{j}-i}{\gamma_{j}+i}, & 1 \leq j \leq N \\
x_{r, N+j}=-(r-1) \ln \frac{\gamma_{j}-i}{\gamma_{j}+i}-(r-1) i \pi, & 1 \leq j \leq N \tag{6}
\end{align*}
$$

In the preceding formula, $\epsilon_{j}$ can be chosen arbitrary, for example it can be fixed in the following way :
$\epsilon_{j}=j$ for $1 \leq j \leq N$, and $\epsilon_{j}=j+1$ for $N+1 \leq j \leq 2 N$.
The link between theta representation of solutions of NLS equation and Fredholm determinant formulation was already presented in [19]. In more details, it is given in a recent paper of Kirillov and Van Diejen [37]. In particular, they compute $\operatorname{det}(I+A)$, where $I$ is the unit matrix and $A=$ $\left(a_{j k}\right)_{1 \leq j, k \leq 2 N}$ the matrix defined as :

$$
\begin{equation*}
a_{j k}=\frac{2 \epsilon_{j} K_{j}}{K_{j}+K_{k}} \prod_{l \neq j}\left|\frac{K_{j}+K_{l}}{K_{j}-K_{l}}\right| \exp \left(-2 K_{j} x\right), \tag{7}
\end{equation*}
$$

where $\epsilon_{j} \in\{-1 ;+1\}$.
Then it is shown that $\operatorname{det}(I+A)$ has the following form

$$
\begin{equation*}
\operatorname{det}(I+A)=\sum_{J \subset\{1, \ldots, N\}} \prod_{j \in J} \epsilon_{j} \prod_{j \in J}\left|\frac{K_{j}+K_{k}}{K_{j}-K_{k}}\right| \exp \left(-2 x \sum_{j \in J} K_{j}\right) . \tag{8}
\end{equation*}
$$

Using the same strategy, we can compute $\operatorname{det}\left(I+A_{r}\right)$ where $A_{r}=\left(a_{\nu \mu}\right)_{1 \leq \nu, \mu \leq 2 N}$ is the matrix defined as :

$$
\begin{equation*}
a_{\nu \mu}=\frac{2(-1)^{\epsilon_{\nu}} \gamma_{\nu}}{\gamma_{\nu}+\gamma_{\mu}} \prod_{\eta \neq \nu}\left|\frac{\gamma_{\nu}+\gamma_{\eta}}{\gamma_{\nu}-\gamma_{\eta}}\right| \exp \left(i K_{\nu}\left(x-x_{0 \nu}\right)-2 \delta_{\nu}\left(t-t_{0 \nu}\right)+x_{r, \nu}\right) . \tag{9}
\end{equation*}
$$

Then $\operatorname{det}\left(I+A_{r}\right)$ has the following form

$$
\begin{equation*}
\operatorname{det}\left(I+A_{r}\right)=\sum_{J \subset\{1, \ldots, 2 N\}} \prod_{\nu \in J}(-1)^{\epsilon_{\nu}} \prod_{\nu \in J \mu \notin J}\left|\frac{\gamma_{\nu}+\gamma_{\mu}}{\gamma_{\nu}-\gamma_{\mu}}\right| \exp \left(i K_{\nu}\left(x-x_{0 \nu}\right)-2 \delta_{\nu}\left(t-t_{0 \nu}\right)+x_{r, \nu}\right) .( \tag{10}
\end{equation*}
$$

From the beginning of this section, $\tilde{\theta}$ has the same expression as in (10) so, we have clearly the equality

$$
\begin{equation*}
\theta_{r}=\operatorname{det}\left(I+A_{r}\right) . \tag{11}
\end{equation*}
$$

Then the solution of NLS equation takes the form

$$
\begin{equation*}
v(x, t)=\frac{\operatorname{det}\left(I+A_{3}(x, t)\right)}{\operatorname{det}\left(I+A_{1}(x, t)\right)} \exp (2 i t-i \varphi) \tag{12}
\end{equation*}
$$

### 2.3 Example

If we consider the case where $N=1$ we get :

$$
\begin{aligned}
& \theta_{3}(x, t)=1-\exp ( \left.-2 \ln \frac{\gamma_{1}-i}{\gamma_{1}+i}+\ln \frac{1+\gamma_{1}^{2}}{1-\gamma_{1}^{2}}+i K_{1}\left(x-x_{01}\right)+2 \delta_{1}\left(t-t_{01}\right)\right) \\
&-\exp \left(-2 \ln \frac{\gamma_{1}-i}{\gamma_{1}+i}+\ln \frac{1+\gamma_{1}^{2}}{1-\gamma_{1}^{2}}+i K_{1}\left(x-x_{01}\right)-2 \delta_{1}\left(t-t_{01}\right)\right) \\
&+\exp \left(i K_{1}\left(x-x_{01}\right)+2 \delta_{1}\left(t-t_{01}\right)\right)
\end{aligned}
$$

It is clearly the expression of $\operatorname{det}\left(I+A_{3}\right)$.

$$
\begin{aligned}
& \theta_{1}(x, t)= 1-\exp \left(\ln \frac{1+\gamma_{1}^{2}}{1-\gamma_{1}^{2}}+i K_{1}\left(x-x_{01}\right)+2 \delta_{1}\left(t-t_{01}\right)\right) \\
&-\exp \left(\ln \frac{1+\gamma_{1}^{2}}{1-\gamma_{1}^{2}}+i K_{1}\left(x-x_{01}\right)-2 \delta_{1}\left(t-t_{01}\right)\right) \\
&+\exp \left(i K_{1}\left(x-x_{01}\right)+2 \delta_{1}\left(t-t_{01}\right)\right) .
\end{aligned}
$$

We refind the expression of $\operatorname{det}\left(I+A_{1}\right)$.
Then we can write clearly the solution of NLS equation in the form

$$
\begin{equation*}
v(x, t)=\frac{\operatorname{det}\left(I+A_{3}(x, t)\right)}{\operatorname{det}\left(I+A_{1}(x, t)\right)} \exp (2 i t-i \varphi) \tag{13}
\end{equation*}
$$

## 3 Expression of solutions of NLS equation in terms of wronkian determinant

### 3.1 Link between Fredholm determinants and wronskians

We consider the following functions

$$
\begin{array}{ll}
\phi_{\nu}(y)=\sin \left(K_{\nu}\left(x-x_{0 \nu}\right) / 2+i \delta_{\nu}\left(t-t_{0 \nu}\right)-i x_{r, \nu} / 2+\gamma_{\nu} y\right), \quad 1 \leq \nu \leq N, \\
\phi_{\nu}(y)=\cos \left(K_{\nu}\left(x-x_{0 \nu}\right) / 2+i \delta_{\nu}\left(t-t_{0 \nu}\right)-i x_{r, \nu} / 2+\gamma_{\nu} y\right), \quad N+1 \leq \nu \leq 2 N . \tag{14}
\end{array}
$$

These functions depend on $r$. We must denote them $\phi_{\nu}^{r}(y)$. For simplicity, in this section we denote them $\phi_{\nu}(y)$.
We use the following notations :
$\Theta_{\nu}=K_{\nu}\left(x-x_{0 \nu}\right) / 2+i \delta_{\nu}\left(t-t_{0 \nu}\right)-i x_{r, \nu} / 2+\gamma_{\nu} y, \quad 1 \leq j \leq 2 N$.
$W_{r}(y)=W\left(\phi_{1}, \ldots, \phi_{2 N}\right)$ is the wronskian $W_{r}(y)=\operatorname{det}\left[\left(\partial_{y}^{\mu-1} \phi_{\nu}\right)_{\nu, \mu \in[1, \ldots, 2 N]}\right]$.
We consider the matrix $D_{r}=\left(d_{\nu \mu}\right)_{\nu, \mu \in[1, \ldots, 2 N]}$ defined by

$$
\begin{aligned}
d_{\nu \mu} & =\frac{2(-1)^{\epsilon_{\nu}} \gamma_{\nu}}{\gamma_{\nu}+\gamma_{\mu}} \prod_{\eta \neq \nu}\left|\frac{\gamma_{\nu}+\gamma_{\mu}}{\gamma_{\nu}-\gamma_{\mu}}\right| \exp \left(i \kappa_{\nu}\left(x-x_{0 \nu}\right)-2 \delta_{\nu}\left(t-t_{0 \nu}\right)+x_{r, \nu}\right), \\
& 1 \leq \nu \leq 2 N, \quad 1 \leq \mu \leq 2 N,
\end{aligned}
$$

with

$$
x_{r, \nu}=(r-1) \ln \frac{\gamma_{\nu}-i}{\gamma_{\nu}+i} .
$$

Then we have the following statement

## Theorem 3.1

$$
\begin{equation*}
\operatorname{det}\left(I+D_{r}\right)=k_{r}(0) \times W_{r}\left(\phi_{1}, \ldots, \phi_{2 N}\right)(0) \tag{15}
\end{equation*}
$$

where

$$
k_{r}(y)=\frac{2^{2 N} \exp \left(i \sum_{\nu=1}^{2 N} \Theta_{\nu}\right)}{\prod_{\nu=2}^{2 N} \prod_{\mu=1}^{\nu-1}\left(\gamma_{\nu}-\gamma_{\mu}\right)}
$$

Proof : We start to remove the factor $(2 i)^{-1} e^{i \Theta_{\nu}}$ in each row $\nu$ in the wronskian $W_{r}(y)$ for $1 \leq \nu \leq 2 N$.
Then

$$
\begin{equation*}
W_{r}=\prod_{\nu=1}^{2 N} e^{i \Theta_{\nu}}(2 i)^{-N}(2)^{-N} \times W_{r 1}, \tag{16}
\end{equation*}
$$

with
$W_{r 1}=\left|\begin{array}{cccc}\left(1-e^{-2 i \Theta_{1}}\right) & i \gamma_{1}\left(1+e^{-2 i \Theta_{1}}\right) & \ldots & \left(i \gamma_{1}\right)^{2 N-1}\left(1+(-1)^{2 N} e^{-2 i \Theta_{1}}\right) \\ \left(1-e^{-2 i \Theta_{2}}\right) & i \gamma_{2}\left(1+e^{-2 i \Theta_{2}}\right) & \ldots & \left(i \gamma_{2}\right)^{2 N-1}\left(1+(-1)^{2 N} e^{-2 i \Theta_{2}}\right) \\ \vdots & \vdots & \vdots & \vdots \\ \left(1-e^{-2 i \theta_{2 N}}\right) & i \gamma_{2 N}\left(1+e^{-2 i \Theta_{2 N}}\right) & \ldots & \left(i \gamma_{2 N}\right)^{2 N-1}\left(1+(-1)^{2 N} e^{-2 i \Theta_{2 N}}\right)\end{array}\right|$
The determinant $W_{r 1}$ can be written as

$$
W_{r 1}=\operatorname{det}\left(\alpha_{j k} e_{j}+\beta_{j k}\right),
$$

where $\alpha_{j k}=(-1)^{k}\left(i \gamma_{j}\right)^{k-1}, e_{j}=e^{-2 i \theta_{j}}$, and $\beta_{j k}=\left(i \gamma_{j}\right)^{k-1}, 1 \leq j \leq N$, $1 \leq k \leq 2 N$, $\alpha_{j k}=(-1)^{k-1}\left(i \gamma_{j}\right)^{k-1}, e_{j}=e^{-2 i \theta_{j}}$, and $\beta_{j k}=\left(i \gamma_{j}\right)^{k-1}, N+1 \leq j \leq 2 N$,
$1 \leq k \leq 2 N$.
Denoting $U=\left(\alpha_{i j}\right)_{i, j \in[1, \ldots, 2 N]}, V=\left(\beta_{i j}\right)_{i, j \in[1, \ldots, 2 N]}$, the determinant of $U$ is clearly equal to

$$
\begin{equation*}
\operatorname{det}(U)=(i)^{\frac{2 N(2 N-1)}{2}} \prod_{2 N \geq l>m \geq 1}\left(\gamma_{l}-\gamma_{m}\right) . \tag{17}
\end{equation*}
$$

Then we use the following Lemma
Lemma 3.1 Let $A=\left(a_{i j}\right)_{i, j \in[1, \ldots, N]}, B=\left(b_{i j}\right)_{i, j \in[1, \ldots, N]}$,
$\left(H_{i j}\right)_{i, j \in[1, \ldots, N]}$, the matrix formed by replacing the $j$ th row of $A$ by the ith row of $B$
Then

$$
\begin{equation*}
\operatorname{det}\left(a_{i j} x_{i}+b_{i j}\right)=\operatorname{det}\left(a_{i j}\right) \times \operatorname{det}\left(\delta_{i j} x_{i}+\frac{\operatorname{det}\left(H_{i j}\right)}{\operatorname{det}\left(a_{i j}\right)}\right) \tag{18}
\end{equation*}
$$

Proof : For $\tilde{A}=\left(\tilde{a}_{j i}\right)_{i, j \in[1, \ldots, N]}$ the transposed matrix in cofactors of $A$, we have the well known formula $A \times{ }^{t} \tilde{A}=\operatorname{det} A \times I$.
So it is clear that $\operatorname{det}(\tilde{A})=(\operatorname{det}(A))^{N-1}$.
The general term of the product $\left(c_{i j}\right)_{i, j \in[1, \ldots, N]}=\left(a_{i j} x_{i}+b_{i j}\right)_{i, j \in[1, \ldots, N]} \times\left(\tilde{a}_{j i}\right)_{i, j \in[1, \ldots, N]}$ can be written as
$c_{i j}=\sum_{s=1}^{N}\left(a_{i s} x_{i}+b_{i s}\right) \times \tilde{a}_{j s}$
$=x_{i} \sum_{s=1}^{N} a_{i s} \tilde{a}_{j s}+\sum_{s=1}^{N} b_{i s} \tilde{a}_{j s}$
$=\delta_{i j} \operatorname{det}(A) x_{i}+\operatorname{det}\left(H_{i j}\right)$.
We get
$\operatorname{det}\left(c_{i j}\right)=\operatorname{det}\left(a_{i j} x_{i}+b_{i j}\right) \times(\operatorname{det}(A))^{N-1}=(\operatorname{det}(A))^{N} \times \operatorname{det}\left(\delta_{i j} x_{i}+\frac{\operatorname{det}\left(H_{i j}\right)}{\operatorname{det}(A)}\right)$.
Thus $\operatorname{det}\left(a_{i j} x_{i}+b_{i j}\right)=\operatorname{det}(A) \times \operatorname{det}\left(\delta_{i j} x_{i}+\frac{\operatorname{det}\left(H_{i j}\right)}{\operatorname{det}(A)}\right)$.
Using the previous lemma (18), we get :

$$
\operatorname{det}\left(\alpha_{i j} e_{i}+\beta_{i j}\right)=\operatorname{det}\left(\alpha_{i j}\right) \times \operatorname{det}\left(\delta_{i j} e_{i}+\frac{\operatorname{det}\left(H_{i j}\right)}{\operatorname{det}\left(\alpha_{i j}\right)}\right),
$$

where $\left(H_{i j}\right)_{i, j \in[1, \ldots, N]}$ is the matrix formed by replacing the jth row of $U$ by the ith row of $V$ defined previously.
We compute $\operatorname{det}\left(H_{i j}\right)$ and we get
$\operatorname{det}\left(H_{i j}\right)=(-1)^{\frac{2 N(2 N+1)}{2}+1}(i)^{\frac{2 N(2 N-1)}{2}} \prod_{2 N \geq l>m \geq 1, l \neq j, m \neq j}\left(\gamma_{l}-\gamma_{m}\right) \prod_{l<j}\left(\gamma_{k}-\gamma_{l}\right) \prod_{l>j}\left(\gamma_{k}-\gamma_{l}\right) .($

We can simplify the quotient $q=\frac{\operatorname{det}\left(H_{i j}\right)}{\operatorname{det}\left(\alpha_{i j}\right)}$ :

$$
\begin{array}{r}
q=\frac{(-1)^{\epsilon(j)} \prod_{l \neq j}\left(\gamma_{l}+\gamma_{k}\right)}{(-1)^{k-1} \prod_{l \neq k}\left(\gamma_{l}-\gamma_{k}\right)} \\
=\frac{(-1)^{\epsilon(j)-k+1} 2 \gamma_{k} \prod_{l \neq k}\left(\gamma_{l}+\gamma_{k}\right)}{\left(\gamma_{j}+\gamma_{k}\right) \prod_{l \neq k}\left(\gamma_{l}-\gamma_{k}\right)} \\
=\frac{(-1)^{\epsilon(j)} 2 \gamma_{k}}{\left(\gamma_{j}+\gamma_{k}\right)} \prod_{l \neq k}\left|\frac{\gamma_{l}+\gamma_{k}}{\gamma_{l}-\gamma_{k}}\right| . \tag{20}
\end{array}
$$

So $\operatorname{det}\left(\delta_{j k} e_{j}+\frac{\operatorname{det}\left(H_{j k}\right)}{\operatorname{det}\left(\alpha_{j k}\right)}\right)$ can be expressed as

$$
\operatorname{det}\left(\delta_{j k} e_{j}+\frac{\operatorname{det}\left(H_{j k}\right)}{\operatorname{det}\left(\alpha_{j k}\right)}\right)=\prod_{j=1}^{2 N} e^{-2 i \Theta_{j}} \operatorname{det}\left(\delta_{j k}+\frac{(-1)^{\epsilon(j)} 2 \gamma_{k}}{\left(\gamma_{j}+\gamma_{k}\right)} \prod_{l \neq k}\left|\frac{\gamma_{l}+\gamma_{k}}{\gamma_{l}-\gamma_{k}}\right| e^{2 i \Theta_{j}}\right) .
$$

Then dividing each column $k$ by $\gamma_{k}, 1 \leq k \leq N$ and multiplying each row $j$ by $\gamma_{j}, 1 \leq j \leq N$, we get

$$
\operatorname{det}\left(\delta_{j k} e_{j}+\frac{\operatorname{det}\left(H_{j k}\right)}{\operatorname{det}\left(\alpha_{j k}\right)}\right)=\prod_{j=1}^{2 N} e^{-2 i \Theta_{j}} \operatorname{det}\left(\delta_{j k}+\frac{(-1)^{\epsilon(j)} 2 \gamma_{j}}{\left(\gamma_{j}+\gamma_{k}\right)} \prod_{l \neq k}\left|\frac{\gamma_{l}+\gamma_{k}}{\gamma_{l}-\gamma_{k}}\right| e^{2 i \Theta_{j}}\right),
$$

and therefore the wronskian

$$
W_{r}\left(\phi_{1}, \ldots, \phi_{N}\right)(0)
$$

can be written as

$$
\prod_{j=1}^{2 N} e^{\left.i \Theta_{j}\right|_{y=0}}(2)^{-2 N}(i)^{\frac{2 N(2 N-2)}{2}} \prod_{j=2}^{2 N} \prod_{i=1}^{j-1}\left(\gamma_{j}-\gamma_{i}\right) \prod_{j=1}^{2 N} e^{-\left.2 i \Theta_{j}\right|_{y=0}} \operatorname{det}\left(I+D_{r}\right)
$$

It follows that

$$
\begin{equation*}
\operatorname{det}\left(I+D_{r}\right)=\frac{e^{i \sum_{j=1}^{2 N} \Theta_{j} \mid y=0} 2^{2 N}}{\prod_{j=2}^{2 N} \prod_{i=1}^{j-1}\left(\gamma_{j}-\gamma_{i}\right)} W_{r}\left(\phi_{1}, \ldots, \phi_{2 N}\right)(0)=k_{r}(0) W_{r}\left(\phi_{1}, \ldots, \phi_{2 N}\right)(0) . \tag{21}
\end{equation*}
$$

So, the solution of NLS equation takes the form

$$
\begin{equation*}
v(x, t)=\frac{k_{3}(0) W_{3}(0)}{k_{1}(0) W_{1}(0)} \exp (2 i t-i \varphi) \tag{22}
\end{equation*}
$$

and we get the following result

Theorem 3.2 The function $v$ defined by

$$
v(x, t)=\frac{W_{3}\left(\phi_{1}, \ldots, \phi_{2 N}\right)(0)}{W_{1}\left(\phi_{1}, \ldots, \phi_{2 N}\right)(0)} \exp (2 i t-i \varphi) .
$$

is solution of the NLS equation (1)

$$
i v_{t}+v_{x x}+2|v|^{2} v=0,
$$

where
$W_{r}(y)=W\left(\phi_{1}, \ldots, \phi_{2 N}\right)$ is the wronskian $W_{r}(y)=\operatorname{det}\left[\left(\partial_{y}^{\mu-1} \phi_{\nu}\right)_{\nu, \mu \in[1, \ldots, 2 N]}\right]$, and $\phi_{\nu}$ the functions given by

$$
\begin{aligned}
& \quad \phi_{\nu}(y)=\sin \left(K_{\nu}\left(x-x_{0 \nu}\right) / 2+i \delta_{\nu}\left(t-t_{0 \nu}\right)-i x_{r, \nu} / 2+\gamma_{\nu} y\right), \quad 1 \leq \nu \leq N, \\
& \phi_{\nu}(y)=\cos \left(K_{\nu}\left(x-x_{0 \nu}\right) / 2+i \delta_{\nu}\left(t-t_{0 \nu}\right)-i x_{r, \nu} / 2+\gamma_{\nu} y\right), \quad N+1 \leq \nu \leq 2 N, \\
& \kappa_{\nu}, \delta_{\nu}, \gamma_{\nu} \text { parameters defined by (4) for } \nu \in[1, \ldots, 2 N]
\end{aligned}
$$

$$
\kappa_{\nu}=2 \sqrt{1-\lambda_{\nu}^{2}}, \quad \delta_{\nu}=\kappa_{\nu} \lambda_{\nu}, \quad \gamma_{\nu}=\sqrt{\frac{1-\lambda_{\nu}}{1+\lambda_{\nu}}}, \quad \epsilon_{\nu} \in\{0 ; 1\}
$$

where $\lambda_{\nu}$ is an arbitrary parameter such that $0<\lambda_{j}<1$ and $\lambda_{N+j}=-\lambda_{j}$ for $j \in[1, \ldots, N]$.

### 3.2 Example

If we consider the simplest case where $N=1$, we get the following results. The wronskian $W_{3}(0)$ is equal to

$$
W_{3}(0)=\frac{1}{\gamma_{1}\left(1+\lambda_{1}\right)} \times\left[\lambda_{1} \cos \left(K_{1}\left(x-x_{01}\right)\right)-\cosh \left(2 \delta_{1}\left(t-t_{01}\right)-x_{1}\right)\right] .
$$

The Fredholm determinant $F_{3}(0)=\operatorname{det}\left(I+A_{3}\right)$ takes the form

$$
\left.F_{3}(0)=\frac{2 e^{i K_{1} x}}{\lambda_{1}} \times\left[\lambda_{1} \cos \left(K_{1}\left(x-x_{01}\right)\right)-\cosh \left(2 \delta_{1}\left(t-t_{01}\right)-x_{1}\right)\right)\right] .
$$

So we have the equality

$$
\operatorname{det}\left(I+A_{3}\right)=C \times W_{3},
$$

with

$$
C=\frac{K_{1} e^{i K_{1} x}}{\lambda_{1}}
$$

If we compute

$$
k_{3}(0)=\frac{2^{2 N} \exp \left(\left.i \sum_{\nu=1}^{2 N} \Theta_{\nu}\right|_{y=0}\right)}{\prod_{\nu=2}^{2 N} \prod_{\mu=1}^{\nu-1}\left(\gamma_{\nu}-\gamma_{\mu}\right)}
$$

we get :

$$
\exp \left(\left.i \sum_{\nu=1}^{2 N} \Theta_{\nu}\right|_{y=0}\right)=e^{i K_{1} x}
$$

$\prod_{\nu=2}^{2 N} \prod_{\mu=1}^{\nu-1}\left(\gamma_{\nu}-\gamma_{\mu}\right)=\gamma_{2}-\gamma_{1}=\frac{1}{\gamma_{1}}-\gamma_{1}=\sqrt{\frac{1+\lambda_{1}}{1-\lambda_{1}}}-\sqrt{\frac{1-\lambda_{1}}{1+\lambda_{1}}}=\frac{2 \lambda_{1}}{\sqrt{1-\lambda_{1}^{2}}}=\frac{2 \lambda_{1}}{K_{1} / 2}=\frac{4 \lambda_{1}}{K_{1}} ;$
So,

$$
k_{3}(0)=\frac{2^{2 N} \exp \left(i \sum_{\nu=1}^{2 N} \Theta_{\nu}\right)}{\prod_{\nu=2}^{2 N} \prod_{\mu=1}^{\nu-1}\left(\gamma_{\nu}-\gamma_{\mu}\right)}=\frac{K_{1} e^{i K_{1} x}}{\lambda_{1}}
$$

and we have the equality

$$
\operatorname{det}\left(I+A_{3}\right)=k_{3}(0) \times W_{3} .
$$

## 4 Construction of quasi-rational solutions of NLS equation

### 4.1 Taking the limit when the parameters $\lambda_{j} \rightarrow 1$ for

 $1 \leq j \leq N$ and $\lambda_{j} \rightarrow-1$ for $N+1 \leq j \leq 2 N$In the following, we show how we can obtain quasi-rational solutions of NLS equation by a rough estimation.
We consider the parameter $\lambda_{j}$ written in the form $1-\epsilon^{2} c_{j}^{2}$. For simplicity, we denote $d_{j}$ the term $\frac{c_{j}}{\sqrt{2}}$.
When $\epsilon$ goes to 0 , we realize limited expansions at order $2 N-1$ of $\kappa_{j}, \gamma_{j}$, $\delta_{j}, x_{r, j}, \kappa_{N+j}, \gamma_{N+j}, \delta_{N+j}, x_{r, N+j}$, for $1 \leq j \leq N$. For example, in the case where $N=1$, it gives:

$$
\begin{aligned}
& \kappa_{j}=4 d_{j} \epsilon+O\left(\epsilon^{2}\right), \quad \gamma_{j}=d_{j} \epsilon+O\left(\epsilon^{2}\right), \quad \delta_{j}=4 d_{j} \epsilon+O\left(\epsilon^{2}\right), \\
& x_{r, j}=(r-1)\left(2 i d_{j} \epsilon+O\left(\epsilon^{2}\right)\right), \\
& \kappa_{N+j}=4 d_{j} \epsilon+O\left(\epsilon^{2}\right), \quad \gamma_{N+j}=1 /\left(d_{j} \epsilon\right)-\left(d_{j} \epsilon\right) / 2+O\left(\epsilon^{2}\right), \quad \delta_{N+j}=-4 d_{j} \epsilon+O\left(\epsilon^{2}\right), \\
& x_{r, N+j}=-(r-1)\left(2 i d_{j} \epsilon+O\left(\epsilon^{2}\right)\right), \\
& 1 \leq j \leq N .
\end{aligned}
$$

Then we realize limited expansions at order $2 N-1$ of the functions $\phi_{j}^{r}(0)$ and $\phi_{N+j}^{r}(0)$, for $1 \leq j \leq N$ :

$$
\begin{aligned}
& \phi_{j}^{1}(0)=\sin E_{j}, \\
& \phi_{j}^{3}(0)=\sin D_{j}, \\
& \phi_{N+j}^{1}(0)=\sin E_{j}^{\prime}, \\
& \phi_{N+j}^{3}(0)=\sin D_{j}^{\prime},
\end{aligned}
$$

with

$$
\begin{aligned}
& D_{j}=K_{j}\left(x-x_{0 j}\right) / 2+i \delta_{j}\left(t-t_{0 j}\right)-i x_{j} / 2, \\
& E_{j}=K_{j}\left(x-x_{0 j}\right) / 2+i \delta_{j}\left(t-t_{0 j}\right), \\
& D_{j}^{\prime}=K_{j}\left(x-x_{0 j}\right) / 2-i \delta_{j}\left(t-t_{0 j}\right)+i x_{j} / 2, \\
& E_{j}^{\prime}=K_{j}\left(x-x_{0 j}\right) / 2-i \delta_{j}\left(t-t_{0 j}\right) .
\end{aligned}
$$

For example, in the case where $N=1$, it gives :

$$
\begin{aligned}
& D_{j}=2 \epsilon d_{j}\left(x-x_{0 j}+2 i\left(t-t_{0 j}\right)+1\right)+O\left(\epsilon^{2}\right), \\
& E_{j}=2 \epsilon d_{j}\left(x-x_{0 j}+2 i\left(t-t_{0 j}\right)\right)+O\left(\epsilon^{2}\right), \\
& D_{j}^{\prime}=2 \epsilon d_{j}\left(x-x_{0 j}-2 i\left(t-t_{0 j}\right)-1\right)+O\left(\epsilon^{2}\right), \\
& E_{j}^{\prime}=2 \epsilon d_{j}\left(\left(x-x_{0 j}-2 i\left(t-t_{0 j}\right)\right)+O\left(\epsilon^{2}\right),\right.
\end{aligned}
$$

and

$$
\begin{aligned}
& \phi_{j}^{1}(0)=2 \epsilon d_{j}\left(x-x_{0 j}+2 i\left(t-t_{0 j}\right)\right)+O\left(\epsilon^{2}\right), \\
& \phi_{j}^{3}(0)=2 \epsilon d_{j}\left(x-x_{0 j}+2 i\left(t-t_{0 j}\right)+1\right)+O\left(\epsilon^{2}\right), \\
& \phi_{N+j}^{1}(0)=1+O\left(\epsilon^{2}\right), \\
& \phi_{N+j}^{3}(0)=1+O\left(\epsilon^{2}\right) .
\end{aligned}
$$

Then according to the relation

$$
v(x, t)=\frac{W_{3}\left(\phi_{1}, \ldots, \phi_{N}\right)(0)}{W_{1}\left(\phi_{1}, \ldots, \phi_{N}\right)(0)} \exp (2 i t-i \varphi)
$$

the solution of NLS equation takes the form :

$$
\begin{aligned}
& v(x, t)=\exp (2 i t-i \varphi) \frac{N(x, t, \epsilon)}{D(x, t, \epsilon)} \\
& =\exp (2 i t-i \varphi)\left|\begin{array}{cccccc}
\sin D_{1} & \ldots & \sin D_{N} & \cos D_{1}^{\prime} & \ldots & \cos D_{N}^{\prime} \\
\gamma_{1} \cos D_{1} & \ldots & \gamma_{N} \cos D_{N} & -\frac{1}{\gamma_{1}} \sin D_{1}^{\prime} & \ldots & -\frac{1}{\gamma_{N}} \sin D_{N}^{\prime} \\
\gamma_{1}^{2} \sin D_{1} & \ldots & \gamma_{N}^{2} \sin D_{N} & \frac{1}{\gamma_{1}^{2}} \cos D_{1}^{\prime} & \ldots & \frac{1}{\gamma_{N}^{2}} \cos D_{N}^{\prime} \\
\vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\
\gamma_{1}^{2 N-1} \cos D_{1} & \ldots & \gamma_{N}^{2 N-1} \cos D_{N} & -\frac{1}{\gamma_{1}^{2 N-1}} \sin D_{1}^{\prime} & \ldots & -\frac{1}{\gamma_{N}^{2 N-1}} \sin D_{N}^{\prime}
\end{array}\right|
\end{aligned}
$$

We use the classical developments
$\sin z=\sum_{j=1}^{N} \frac{(-1)^{j-1} z^{2 j-1}}{(2 j-1)!}+O\left(z^{2 N}\right)$ and $\cos z=\sum_{j=0}^{2 N} \frac{(-1)^{j} z^{2 j}}{(2 j)!}+O\left(z^{2 N+1}\right)$, for $z$ in a neighborhood of 0 .
Using the fact that $D_{j}=E_{j}+\alpha_{j}(\epsilon), D_{j}^{\prime}=E_{j}^{\prime}-\alpha_{j}(\epsilon)$, and addition formulas for trigonometric functions, we can expand the numerator $N(x, t, \epsilon)$ along the columns; it takes the form of

$$
\prod_{j=1}^{N} \cos ^{2}\left(\alpha_{j}(\epsilon)\right) D(x, t, \epsilon)+A
$$

If we divide each term of this sum by $D(x, t)$, when $\epsilon$ tends to 0 , the first term tends to 1 ; in each other term of the sum of $A$, we can multiply each fraction by some power of $\gamma_{j}$ to get a finite limit when $\epsilon$ goes to 0 .
So we get really a non trivial and non degenerate quotient of two polynomials in $x$ and $t$ by an exponential.
Practically, we keep only the terms of lower degree in $\epsilon$, in numerator and denominator which expressed as powers of $x$ and $t$
So we get in this way a quasi-rational solution of the NLS equation.
So we get the following result

Theorem 4.1 The function $v$ defined by

$$
v(x, t)=\lim _{\epsilon \rightarrow 0} \frac{W_{3}\left(\phi_{1}, \ldots, \phi_{2 N}\right)(0)}{W_{1}\left(\phi_{1}, \ldots, \phi_{2 N}\right)(0)} \exp (2 i t-i \varphi) .
$$

is a quasi-rational solution of the NLS equation (1)

$$
i v_{t}+v_{x x}+2|v|^{2} v=0
$$

where
$W_{r}(y)=W\left(\phi_{1}, \ldots, \phi_{2 N}\right)$ is the wronskian $W_{r}(y)=\operatorname{det}\left[\left(\partial_{y}^{\mu-1} \phi_{\nu}\right)_{\nu, \mu \in[1, \ldots, 2 N]}\right]$, and $\phi_{\nu}$ the functions given by

$$
\phi_{\nu}(y)=\sin \left(K_{\nu}\left(x-x_{0 \nu}\right) / 2+i \delta_{\nu}\left(t-t_{0 \nu}\right)-i x_{r, \nu} / 2+\gamma_{\nu} y\right), \quad 1 \leq \nu \leq N
$$

$$
\phi_{\nu}(y)=\cos \left(K_{\nu}\left(x-x_{0 \nu}\right) / 2+i \delta_{\nu}\left(t-t_{0 \nu}\right)-i x_{r, \nu} / 2+\gamma_{\nu} y\right), \quad N+1 \leq \nu \leq 2 N,
$$

$\kappa_{\nu}, \delta_{\nu}, \gamma_{\nu}$ parameters defined by (4) for $\nu \in[1, \ldots, 2 N]$

$$
\kappa_{\nu}=2 \sqrt{1-\lambda_{\nu}^{2}}, \quad \delta_{\nu}=\kappa_{\nu} \lambda_{\nu}, \quad \gamma_{\nu}=\sqrt{\frac{1-\lambda_{\nu}}{1+\lambda_{\nu}}}, \quad \epsilon_{\nu} \in\{0 ; 1\}
$$

where $\lambda_{j}=1-\epsilon^{2} c_{j}^{2}$ is an arbitrary parameter such that $0<\lambda_{j}<1$ and $\lambda_{N+j}=-\lambda_{j}, c_{j}$ an arbitrary real number, for $j \in[1, \ldots, N]$,

If we want to recover exact solution of Akhmediev type, we must more precise in the estimations.

### 4.2 Examples

For brevity, in the following we choose $x_{0 i}=0, t_{0 i}=0$ and $\varphi=0$ for $1 \leq i \leq 2 N$.

If we consider the case $N=1$, from (22), we realize a development at order 1 of $W_{3}$ and $W_{1}$ in $\epsilon$. The solution of NLS equation can be written as

$$
v(x, t)=-\frac{\left(-4 x^{2}-16 t^{2}+16 i t+3\right)}{\left.4 x^{2}+16 t^{2}+1\right)} \exp (2 i t) .
$$

Then $v$ takes the form

$$
v(x, t)=1-4 \frac{1+4 i t}{1+16 t^{2}+4 x^{2}} \exp (2 i t) .
$$

If we make the following changes of variables $t \rightarrow X / 2$ and $x \rightarrow T$, we get exactly first order Akhmediev's solution (see [1]).

$$
v(x, t)=\left(1-\frac{4(1+2 i x)}{1+4 x^{2}+4 t^{2}}\right) \exp (i x) .
$$

In the case $N=2$, we must realize a development at order 3 in $\epsilon$. From (22), the solution of NLS equation can be written as

$$
v(x, t)=\frac{N(x, t)}{D(x, t)} \exp (2 i t)
$$

with
$N(x, t)=5760 x^{2} t^{2}-3072 x^{2} t^{4}+1872 t^{2}-64 x^{6}-45-4096 t^{6}+180 x^{2}+144 x^{4}-768 x^{4} t^{2}$

$$
+768 i x^{4} t+8448 t^{4}-1152 i x^{2} t+1536 i t^{3}-720 i t+12288 i t^{5}+6144 i t^{3} x^{2}
$$

and
$D(x, t)=-1152 x^{2} t^{2}+3072 x^{2} t^{4}+1584 t^{2}+64 x^{6}+9+4096 t^{6}+108 x^{2}+48 x^{4}+768 x^{4} t^{2}+6912 t^{4}$.
If we make the following changes of variables $t \rightarrow X / 2$ and $x \rightarrow T$, we get

$$
v(x, t)=\frac{N_{1}(x, t)}{D_{1}(x, t)} \exp (i x),
$$

with

$$
\begin{aligned}
N_{1}(x, t)= & 1440 x^{2} t^{2}-192 x^{4} t^{2}+468 x^{2}-64 t^{6}-45-64 x^{6}+180 t^{2}+144 t^{4}-192 x^{2} t^{4}-576 i t^{2} x \\
& +528 x^{4}+384 i x^{5}+192 i x^{3}-360 i x+384 i t^{4} x+768 i x^{3} t^{2},
\end{aligned}
$$

and
$D_{1}(x, t)=-288 x^{2} t^{2}+192 x^{4} t^{2}+396 x^{2}+64 t^{6}+9+64 x^{6}+108 t^{2}+48 t^{4}+192 x^{2} t^{4}+432 x^{4}$.
It can be reduced exactly at the second order Akhmediev's solution (see [1]).
$v(x, t)=1+\frac{3 / 8-3 t^{2}-2 t^{4}-9 x^{2}-10 x^{4}-12 t^{2} x^{2}+i x\left(15 / 4+6 t^{2}-4 t^{4}-2 x^{2}-4 x^{4}-8 t^{2} x^{2}\right)}{3 / 32+9 / 8 t^{2}+1 / 2 t^{4}+2 / 3 t^{6}+33 / 8 x^{2}+9 / 2 x^{4}+2 / 3 x^{6}-3 t^{2} x^{2}+2 t^{4} x^{2}+2 t^{2} x^{4}} \exp (i x)$.
This method can be extended to get quasi-rational solutions of NLS equation at any order.

## 5 Conclusion

Here is given a new formulation of solutions of NLS equation that gives as particular case, Akhmediev's solutions. These solutions expressed as a quotient of wronskians are similar to a previous result of Eleonski, Krichever and Kulagin [13]. Their formulation can also be seen as a quotient of two wronkians but is more complicated because it needs recursion operations. However, it can be used to get solutions of NLS equation (see [12]).
This new formulation can give explicitly a set of non singular solutions of NLS equation which can be obtained by a simpler way than with the Krichever method.

## References

[1] N. Akhmediev, A. Ankiewicz, J.M. Soto-Crespo, Rogue waves and rational solutions of nonlinear Schrödinger equation, Physical Review E, V. 80, N. 026601, 2009
[2] N. Akhmediev, V. Eleonsky, N. Kulagin, Exact first order solutions of the nonlinear Schrödinger equation, Th. Math. Phys., V. 72, N. 2, 183-196, 1987
[3] N. Akhmediev, A. Ankiewicz, J.M. Soto-Crespo, Waves that appear from nowhere : on the nature of rogue waves, Physical Letters A, V. 373, 2137-2145, 2009
[4] N. Akhmediev, A. Ankiewicz, First-order exact solutions of the nonlinear Schrödinger equation in the normal-dispersion regime, Physical Review A, V. 47, N. 4, 3213-3221, 2009
[5] N. Akhmediev, A. Ankiewicz, M. Taki, Waves that appear from nowhere and disappear without a trace, Physical Review A, V. 373, 675-678, 2009
[6] N. Akhmediev, A. Ankiewicz, J.M. Soto-Crespo, Pulsating, creeping and erupting solitons in dissipative systems, Physical Review Letters, V. 85, N. 14, 2937-2940, 2000
[7] N. Akhmediev, V. Eleonsky, N. Kulagin, Generation of periodic trains of picosecond pulses in an optical fiber : exact solutions, Sov. Phys. J.E.T.P., V. 62, 894-899, 1985
[8] N. Akhmediev, Y.V. Bludov, V.V. Konotop, Matter rogue waves, Physica Scripta, V. 50, 9-12, 1994
[9] E.D. Belokolos, A.I. Bobenko, A.R. Its, V.Z. Enolskij and V.B. Matveev, Algebro-geometric approach to nonlinear integrable equations, Springer series in nonlinear dynamics, Springer Verlag, 1-360, (1994).
[10] R. Beutler, A. Stahlhofen, V.B. Matveev, What do solitons, breathers and positons have in common? Physica Scripta, V. 50, 9-12, (1994).
[11] B.A. Dubrovin, V.B. Matveev, S.P. Novikov, in Lond. Math. Soc. Lect. Notes Ser., V. 60, 55-136, Cambridge University Press, (1981).
[12] P. Dubard, P. Gaillard, C. Klein, V.B. Matveev, On multi-rogue waves solutions of the NLS equation and positon solutions of the KdV equation , Eur. Phys. J. Special Topics, V. 185, 247-258, 2010X
[13] V. Eleonski, I. Krichever, N. Kulagin, Rational multisoliton solutions to the NLS equation, Soviet Doklady 1986 sect. Math. Phys., 287, 606-610, (1986)
[14] P. Gaillard, V.B. Matveev, Wronskian addition formula and its applications, Max-Planck-Institut für Mathematik, Bonn, MPI 02-31, 1-17, (2002).
[15] P. Gaillard, A new family of deformations of Darboux-Pöschl-Teller potentials, Letters in Mathematical Physics, V 68, 77-90, (2004).
[16] P. Gaillard, From finite-gap solutions of KdV in terms of theta functions to solitons and positons, preprint, hal-00466159, (2010).
[17] R. Hirota, Phys. Rev. Letters, V. 27, 1192, (1971).
[18] A.N.W Hone, J. Phys. A : Math. Gen., V. 30, 7473-7483, (1997).
[19] A.R. Its, A.V. Rybin, M.A. Salle, Exact integration of nonlinear Schrödinger equation, Teore. i Mat. Fiz., V. 74., N. 1, 29-45, (1988).
[20] A.R. Its, V.B. Matveev, Hill's operator with finitely many gaps, Funct. Anal. i Prilozhen, V. 9., 69-70, (1975).
[21] M. Kovalyov, M.H Ali Abadi, An explicit formula for a class of solutions of KdV equation, University of Alberta, Canada, (1997).
[22] M. Jaworski, J. Zagrodzinski, Positon and positon-like solution of the Korteweg-de Vries and Sine-Gordon equations, Chaos Solitons Fractals, V. 5, N. 12, 2229-2233, (1995).
[23] V.B. Matveev, Lett. Math. Phy., V. 3, 213-216, 217-222, (1979).
[24] V.B. Matveev, Asymptotics of the multipositon-soliton $\tau$ function of the Korteweg-de Vries equation and the supertransparency, J. Math. Phys., V. 125, N. 6, 2955-2970, (1994).
[25] V.B. Matveev, M.A. Salle, Darboux transformations and solitons, Series in Nonlinear Dynamics, Springer Verlag, Berlin, (1991).
[26] V.B. Matveev, M.A. Salle, Darboux transformations and coherent interaction of the light pulses with two level media, Inverse Problems, V. 4, 175-183, (1988).
[27] V.B. Matveev, Multi positons solutions of the KdV equation. Positonpositon and soliton-positon interactions, Preprint, (1998).
[28] V.B. Matveev, Positon-positon and soliton-positon collisions : KdV case, Phys. Let. A, V. 166, 208-212, (1992).
[29] V.B. Matveev, Asymptotics of mulpositon-solution $\tau$ function of the Korteweg-de Vries equation and the supertransparency, J. Math. Phys., V. 35, N. 6, (1994).
[30] V.B. Matveev, Positon : slowly decreasing analogues of solitons, Th. And Math. Phys. V. 131, N. 1, (2002).
[31] D. Pelinovsky, On a structure of the explicit solutions of the DaveyStewartson equations, Phys. D, V. 87, 115-122, 1995
[32] D. Peregrine, Water waves, nonlinear Schrödinger equations and teir solutions, J. Austral. Math. Soc. Ser. B, 16-43, 1983
[33] C. Rasinariu, U. Sukhatme, A. Khare, Negaton and positon solutions of the KdV and the mKdV hierarchy, J. Phys. A, V. 29, 1803-1823, London, (1996).
[34] A.A. Stahlhofen, V.B. Matveev, Positons for the Toda lattice and related spectral problems, J. Phys. A. : Math. Gen., V 28, 1957-1965, (1995).
[35] J.F. Van Diejen, A.N. Kirillov, Formulas for q-Spherical functions using inverse scattering theory of reflectionless Jacobi operators, Commun. Math. Phys., V. 210, 335-369, (2000).
[36] J. F. Van Diejen, Integrabilty of difference Calogero-Moser systems, Jour. of Math. Physics, V. 35 N. 6, 2983-3004, (1999).
[37] J.F. Van Diejen, A. N. Kirillov Determinantal formulas for zonal spherical functions on hyperboloids, Math. Ann., V. 319, 215-234, (2001).
[38] A. Zabrodin, Finite-gap difference operators with elliptic coefficients and their spectral curves, in "Physical Combinatorics", M. Kashiwara and T. Miwa (eds), Birkhauser Ser. Progress in Mathematics, V. 191, ISBN 0-816-4175-0, Birkhauser-Boston, 301-317, (2000).
[39] H. Zhao, Z. Zhu, Multi-soliton, multi-positon, multi-negaton, and multiperiodic solutions of the coupled Volterra lattice equation, arXiv : 0911.3458 v 1 [nlin.S1], 18 nov 2009

