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Ambiguity preferences for health

ARTHUR E. ATTEMA

Department of Health Policy & Management, Erasmus University Rotterdam, attema@bmg.eur.nl

HAN BLEICHRODT

Erasmus School of Economics & Department of Health Policy & Management, Erasmus University
Rotterdam,

Research School of Economics, Australian National University, Canberra, bleichrodt@ese.eur.nl

OLIVIER L'HARIDON

University of Rennes 1, lharidon@univ-rennes1.fr

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Abstract

In most medical decisions probabilities are ambiguous and not objectively known.

Empirical evidence suggests that people's preferences are affected by ambiguity. Health economic analyses generally ignore ambiguity preferences and assume that they are the same as preferences under risk. We show how health preferences can be measured under ambiguity and we compare them with health preferences under risk. We assume a general ambiguity model that includes many of the ambiguity models that have been proposed in the literature. For health gains, ambiguity preferences and risk preferences were indeed the same. For health losses they differed with subjects being more pessimistic in decision under ambiguity. Utility and loss aversion were the same for risk and ambiguity.

Key words: ambiguity, health.

JEL classification: D81, D91, I12.

1. Introduction

In the early 1990s Pauker and Kopelman wrote a series of articles in the *New England Journal of Medicine* about cases in clinical decision making (e.g. Pauker and Kopelman, 1992a; Pauker and Kopelman, 1992b; Pauker and Kopelman, 1993; Pauker and Kopelman, 1994a; Pauker and Kopelman, 1994b). A common theme of these cases is ambiguity about the correct diagnosis. The case studies are full of words as “likely”, “maybe”, “I don’t expect”, “I am not aware”, etc. Usually several illnesses are possible and all the clinician can do is to assess their likelihood. Objective probabilities are never available.

Ambiguity is common in health decision making. The recent emphasis on evidence-based medicine has highlighted that opinions conflict and that evidence is generally ambiguous. Ambiguity permeates not only clinical decision making, but also other health decisions such as the adoption of healthy lifestyles, the choice of an insurance scheme, and public health decisions.

In spite of the ubiquity of ambiguity in health, the question how people make health decisions under ambiguity has been largely ignored. There is a rich literature on health decision making under risk (where probabilities are objectively known), but very little attention has been paid to the arguably more realistic case where objective probabilistic information is missing. The most common approach is to assume that ambiguous prospects are treated similarly as risky prospects by replacing objective probabilities by the decision maker’s subjective beliefs. This approach implicitly assumes that the decision maker is neutral towards ambiguity.

The assumption of ambiguity neutrality is questionable. Keynes (1921) already pointed out that people’s preferences over ambiguous prospects depend not only on their subjective beliefs, but also on the confidence they have in those beliefs. Ellsberg’s

(1961) famous paradox¹ showed that people usually prefer situations with known risks to situations with unknown risks. Empirical studies have confirmed such ambiguity aversion. Most of this evidence involves money and there is little evidence on ambiguity and health. An exception is Curley et al. (1984) who found ambiguity aversion for health, which differed from ambiguity aversion for money. This domain-specificity of ambiguity preferences is consistent with studies on risk and time preferences which found that findings for money cannot be directly translated to health (Attema et al., 2017; Chapman, 1996; Hardisty and Weber, 2009; Weber et al., 2002).

Many models have been proposed to explain ambiguity aversion (Gilboa and Marinacci, 2016). Broadly speaking, these models can be subdivided into two classes. The first class explains ambiguity aversion through a difference in utility between risk (known probabilities) and ambiguity (unknown probabilities). We refer to this class as the *source-dependent utility* (SDU) class. The best-known SDU model is the smooth ambiguity model of Klibanoff et al. (2005).² The second class explains ambiguity aversion through a difference in the weighting of events under risk and ambiguity. We refer to this class as the *source-dependent weighting* (SDW) class. The best-known SDW model is prospect theory (Kahneman and Tversky, 1979; Tversky and Kahneman, 1992).³ The empirical literature is divided as to which of these models best describes people's ambiguity preferences (Baillon and Bleichrodt, 2015; Chew et al., forthcoming;

¹ Ellsberg's paradox is a thought experiment in which a decision maker has to choose between betting on a known urn containing 50 red and 50 black balls and an unknown urn containing 100 red and black balls in unknown proportion. Ellsberg conjectured that the decision maker would prefer to bet on the known urn if red was the winning color, but also when black was the winning color. Such preferences violate subjective expected utility (in fact, they even violate probabilistic sophistication (Machina and Schmeidler, 1992)). Many subsequent experimental studies confirmed Ellsberg's conjecture.

² Other models that belong to the SDU class are those of Nau (2006), Chew et al. (2008), Seo (2009), Ergin and Gul (2009), and Neilson (2010).

³ Other examples are the multiple priors models (Ghirardato et al., 2004; Gilboa and Schmeidler, 1989; Jaffray, 1989) and modifications thereof (Gajdos et al., 2008; Maccheroni et al., 2006), multiplier preferences (Hansen and Sargent, 2001; Strzalecki, 2011), vector expected utility (Siniscalchi, 2009), and Choquet expected utility (Gilboa, 1987; Schmeidler, 1989; Wakker, 1987).

Cubitt et al. 2014). The few theoretical applications of ambiguity aversion to health have mostly used the smooth model (e.g. Berger et al., 2016; Berger et al., 2013; Etner and Spaeter, 2010; Treich, 2010), but empirical evidence supporting that people indeed behave according to the smooth model does not exist for health.⁴

This paper investigates in detail people's ambiguity preferences for health. Because ambiguity attitudes are usually sign-dependent (Trautmann and van de Kuilen, 2015), we consider both gains and losses in health. We assume a very general model of decision under ambiguity that includes most of the ambiguity models that have been proposed in the literature as special cases and we show how this general model can be measured. We measure utility (including loss aversion) and event weights for health gains and losses for both risk and ambiguity. This allows us to answer the question whether ambiguity and risk preferences for health differ and whether the common approach in health economics to equate the two is justified. It also allows drawing some inferences about the descriptive validity of the SDU and SDW ambiguity models in health.

We found that risk and ambiguity preferences were the same for health gains. For health losses, we found a difference in event weighting, which indicated more pessimism for ambiguity than for risk. Utility was the same for health losses under risk and ambiguity. The empirical shapes of utility and event weighting were largely consistent with the assumptions of prospect theory. We found convex utility for losses, but utility for gains was linear. Our subjects were loss averse for both risk and ambiguity with loss aversion coefficients around 1.5. Event weighting had the common inverse S-shape meaning that subjects were sensitive to changes in likelihood for very unlikely and very likely events but less so for intermediate changes in likelihood.

⁴ On the other hand, Asano and Shibata (2011) use Gilboa and Schmeidler's (1989) maxmin expected utility model and Anwar and Zheng (2012) use Choquet expected utility.

2. Background

A decision maker has to make a choice under ambiguity. Ambiguity is modeled through a set of states of the worlds S . Exactly one of the states will obtain, but the decision maker does not know which one. Subsets E of S are called *events* and E^c denotes the complement of E .

The decision maker has preferences over *health prospects* involving life duration. These preferences are denoted by the symbols $>$, \succcurlyeq , and \sim , which stand for strict preference, weak preference, and indifference, respectively. Preferences are defined relative to a reference point x_0 . *Gains* are outcomes strictly preferred to x_0 and *losses* are outcomes strictly less preferred than x_0 . Health prospects are denoted $x_E y$, signifying that the decision maker lives for $x + x_0$ years if event E occurs and for $y + x_0$ years otherwise. We assume that the decision maker prefers more life-years to less. This excludes health states worse than death and health states for which there is a maximal endurable time (Stalmeier et al., 2007). If probabilities are known, we will write $x_p y$ for the prospect that gives life duration $x + x_0$ years with probability p and life duration $y + x_0$ years with probability $1 - p$. We will refer to $x_E y$ as an *ambiguous prospect* (meaning that probabilities are unknown) and to $x_p y$ as a *risky prospect* (meaning that probabilities are known).

A prospect is *mixed* if it involves both a gain and a loss. For mixed prospects the notation $x_E y$ signifies that x is a gain and y is a loss. A *gain prospect* involves no losses (i.e. both x and y are weakly preferred to x_0) and a *loss prospect* involves no gains. For gain prospects the notation $x_E y$ signifies that $x \geq y$ and for losses it signifies that $x \leq y$.

We assume that the decision maker evaluates mixed prospects $x_E y$ as:

$$W^+(E)U(x) + W^-(E^c)U(y), \quad (1a)$$

and gain or loss prospects as:

$$W^i(E)U(x) + (1 - W^i(E))U(y), \quad (1b)$$

where $i = +$ for gains and $i = -$ for losses. U is a strictly increasing, real-valued *utility function* that satisfies $U(x_0) = 0$. The utility function is a ratio scale and we can choose the utility of one outcome other than the reference point. U is an overall utility function that includes loss aversion.

The *event weighting functions* $W^i, i = +, -$, assign a number $W^i(E)$ to each event E such that

$$(i) \quad W^i(\emptyset) = 0$$

$$(ii) \quad W^i(S) = 1$$

$$(iii) \quad W^i \text{ is monotonic: } E \supseteq F \text{ implies } W^i(E) \geq W^i(F).$$

The event weighting functions W^i may be different for gains and losses and they need not to be additive. If they are additive, the event weights are subjective probabilities and Eqs. (1a-b) become equivalent to subjective expected utility.

The model described in Eqs. (1a) and (1b) is referred to in the literature as *biseparable preferences* (Ghirardato and Marinacci, 2001). It is very general and includes many of the ambiguity models that have been proposed in the literature as special cases (Wakker, 2010). For that reason we take it as our structural assumption and measure its distinct components.

Mixed risky prospects $x_p y$ are evaluated under biseparable preferences as:

$$w^+(p)u(x) + w^-(1-p)u(y) \quad (2a)$$

and gain and loss risky prospects $x_p y$ as

$$w^i(p)u(x) + (1 - w^i(p))u(y), i = +, -. \quad (2b)$$

w^i is a strictly increasing *probability weighting function* that satisfies $w^i(0) = 0$ and $w^i(1) = 1$ and that may also differ between gains and losses. u is a strictly increasing real-valued utility function that satisfies $u(x_0) = 0$. Hence, in the evaluation of risky prospects the event weighting functions W^i are replaced by probability weighting functions w^i and the utility function U is replaced by u .

By comparing utility and event weighting under risk and ambiguity we can evaluate whether preferences under risk can be used to inform preferences under ambiguity. This comparison also allows us to test the descriptive validity of the SDU and the SDW models for health. The SDU models assume that $W^i = w^i$ and they model ambiguity aversion by a difference between U and u . More precisely, the decision maker is ambiguity averse [seeking] in the SDU models if U is a concave [convex] transformation of u . On the other hand, the SDW models assume that $U = u$ and they model ambiguity aversion by means of a difference between W^i and w^i . In the SDW models, ambiguity aversion [seeking] for gains means that W^+ lies below [above] w^+ , ambiguity aversion [seeking] for losses means that W^- lies above [below] w^- .

3. Measurement method

We used the method of Abdellaoui et al. (2016) to measure U and u in Eqs. (1a-b) and (2a-b). By adding a few questions we could also measure W^i and w^i , $i = +, -$. We imposed

no simplifying parametric assumptions on utility, loss aversion, probability weighting, or event weighting. Consequently, our measurements are entirely parameter-free.

Table 1 summarizes the four stages of the measurements. The first three stages measured utility for gains and losses, the fourth stage measured event/probability weighting. We will describe the measurement procedure for ambiguity. The measurements for risk follow by replacing the event E by a given probability p .⁵ The third column of Table 1 shows the quantity that was assessed in each of the four stages of the procedure. The fourth column shows the indifference that was elicited. The fifth column shows the implication of the elicited indifference. The sixth column shows the stimuli that we used in the experiment reported in Section 4.

Table 1: The four-stage measurement method

		Assessed quantity	Indifference	Implication	Stimuli
Stage 1		L	$G_E L \sim 0$	$U(x_1^+) = -U(x_1^-)$	$G = 32$ months Unc.: $E = [.3, .7]$ Risk: $p = \frac{1}{2}$
		x_1^+	$x_1^+ \sim G_E 0$		
		x_1^-	$x_1^- \sim L_E c 0$		
Stage 2	Step 1	\mathcal{L}	$x_{1E}^+ \mathcal{L} \sim \ell_E c 0$	$U(x_j^+) - U(x_{j-1}^+)$ $= U(x_1^+) - U(x_0)$	$\ell = -6$ months $j = 2, \dots, 5$
	Step 2 to 5	x_j^+	$x_j^+ \mathcal{L} \sim x_{j-1E}^+ \ell$		
Stage 3	Step 1	\mathcal{G}	$G_E x_1^- \sim \vartheta_E 0$	$U(x_j^-) - U(x_{j-1}^-)$ $= U(x_1^-) - U(x_0)$	$\vartheta = 6$ months $j = 2, \dots, 5$
	Step 2 to 5	x_j^-	$G_E x_j^- \sim \vartheta_E x_{j-1}^-$		
Stage 4	Gains	x_E^+	$x_E^+ \sim x_{5E}^+ 0$	$U(x_E^+) = W^+(E)$ $U(x_E^-) = W^-(E)$	Unc.: $E =$ [0, .2], [1, .5], [.3, .7], [.5, .9], [.8, 1] Risk: $p =$ 0.1, 0.3, 0.5, 0.7, 0.9
	Losses	x_E^-	$x_E^- \sim x_{5E}^- 0$		

The first stage established the link between utility for gains and utility for losses by eliciting a gain and a loss with the same absolute utility. We started by selecting an event E and a gain G . Then we elicited the loss L for which $G_E L \sim x_0$ and certainty equivalents x_1^+ and x_1^- such that $x_1^+ \sim G_E x_0$ and $x_1^- \sim L_E c x_0$. Abdellaoui et al. (2016) showed that these

⁵ The reader not interested in the technical details of our measurements can easily skip these and move on to Section 4.

three indifferences imply that

$$U(x_1^+) = -U(x_1^-). \quad (3)$$

In other words, x_1^+ and x_1^- are a gain and a loss that have the same absolute utility.

In the second stage, we used x_1^+ and the trade-off method of Wakker and Deneffe (1996) to elicit a sequence of gains x_2^+, \dots, x_5^+ for which the utility difference between successive elements was constant. Let ℓ be a prespecified loss. We first elicited the loss \mathcal{L} such that the subject was indifferent between $x_1^+ \mathcal{L}$ and $\ell_E x_0$. This established a gauge that we used next to elicit a series of indifferences $x_j^+ \mathcal{L} \sim x_{j-1}^+ \ell, j = 2, \dots, 5$. Wakker and Deneffe (1996) showed that the utility difference between the successive elements of the sequence x_0, x_1^+, \dots, x_5^+ is constant: $U(x_j^+) - U(x_{j-1}^+) = U(x_1^+) - U(x_0), j = 2, \dots, 5$.

The third stage was similar to the second except that we used x_1^- to construct a sequence of losses x_0, x_1^-, \dots, x_5^- for which the utility difference between successive elements was constant. We selected a gain \mathcal{G} and an event E and elicited the gain \mathcal{G} such that $\mathcal{G}_E x_1^- \sim \mathcal{G}_E x_0$. We then proceeded to elicit the sequence $\{x_0, x_1^-, x_2^-, \dots, x_{k_L}^-\}$ by eliciting a series of indifferences $\mathcal{G}_E x_j^- \sim \mathcal{G}_E x_{j-1}^-, j = 2, \dots, k_L$.

Because $U(x_1^+) = U(x_1^-)$, the second-stage and third-stage sequences could be combined to obtain a sequence $\{x_5^-, \dots, x_1^-, x_0, x_1^+, \dots, x_5^+\}$ that ran from the domain of losses through the reference point to the domain of gains and for which the utility difference between successive elements was constant. We scaled utility by setting $U(x_5^+) = 1$, which is allowed by the uniqueness properties of biseparable preferences. It follows that $U(x_j^+) = j/5$ and $U(x_j^-) = -j/5$, for $j = 1, \dots, 5$.

In the fourth stage we used the elicited sequence $\{x_5^-, \dots, x_1^-, x_0, x_1^+, \dots, x_5^+\}$ to measure the probability and the event weights. For an event E , we measured $W^+(E)$ by eliciting the certainty equivalent x_E^+ of the prospect (x_5^+, E, x_0) . Then $U(x_E^+) = W^+(E) \cdot U(x_5^+)$. $U(x_E^+)$ can be approximated from the utility function for ambiguity that was measured in the second stage. Similarly, we measured $W^-(E)$ by eliciting the certainty equivalent x_E^- of the prospect (x_5^-, E, x_0) . We varied E to measure 5 points of W^i , $i = +, -$. Similarly, we used 5 probabilities to measure the probability weighting functions w^i , $i = +, -$.

4. Experiment

4.1. Subjects

Subjects were 65 students of the Erasmus University (27 female). Each subject was paid a €10 participation fee. Data were collected by individual interviews to maximize data quality. The experiment was computer-run. Subjects first received instructions about the tasks. They were told that there were no right or wrong answers and that we were only interested in their preferences. We emphasized that they should go through the experiment at their own pace. After the instructions, subjects completed ten practice questions. Then they started with the actual experiment. The experimental instructions are in the online Appendix. Prior to the actual experiment, we did an extensive pilot study, which mainly served to fine-tune the implementation of the ambiguity questions.

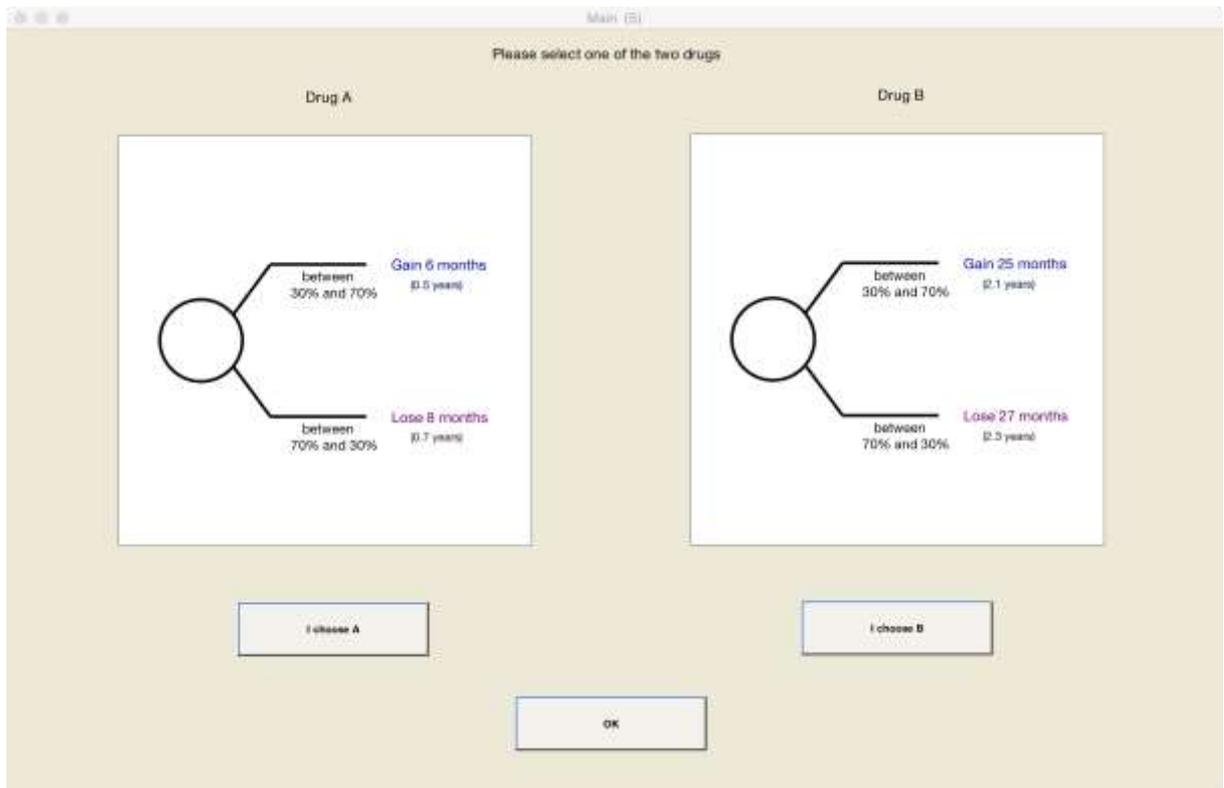
4.2. Procedure and stimuli

Table 1 shows the values of the parameters that we specified in advance. We told

subjects to imagine living with a disease that restricted their life-expectancy to 50 more years, but which did not affect their quality of life. These 50 years are about 10 years less than the life-expectancy of the average subject in our sample. The disease required taking a drug with no side-effects. If the subject would not take a drug he would die immediately. Subjects were asked to choose between two drugs that had two possible outcomes. Under risk, the success rates of the drugs were objectively given. Under ambiguity, we specified a range of possible success rates. This implementation of ambiguity was similar to Curley et al. (1984) and Curley and Yates (1985).

The outcomes of the two drugs were described as gains and losses in life-expectancy from 50 years. By presenting the choices this way we hoped that subjects would take 50 years as their reference point. This strategy has been successfully applied before by Attema et al. (2013). Figure 1 shows the presentation of the choices under ambiguity. The choices under risk were similar except that in these the success rates were objectively given.

Figure 1: Presentation of the choices under ambiguity



For both gains and losses, we elicited five points of the utility function under both risk and ambiguity. For risk, we elicited the weights of five probabilities for both gains and losses: 0.1, 0.3, 0.5, 0.7, 0.9. These include a probability that is usually overweighted (0.1), two probabilities that are usually underweighted (0.7 and 0.9) and two probabilities for which usually little weighting is observed (0.3 and 0.5) (Fox and Poldrack, 2014). For ambiguity, we presented subjects with an interval within which the imprecise success rates could lie. The centers of these intervals were equal to the success rates considered for risk. Their ranges were [0, 0.2], [0.1, 0.5], [0.3, 0.7], [0.5, 0.9], and [0.8, 1]. So for the smallest and largest success rate the range of possible probabilities was 0.2, for the other probabilities it was 0.4. Curley and Yates (1985) found no effect of the (nonzero) range of probabilities on ambiguity attitudes.

We used a choice-based procedure to elicit indifference values. The procedure zoomed in on subjects' indifference values by an iterative series of binary choices. Previous research

suggests that choice-based elicitation leads to more reliable results than asking subjects directly for their indifference values (Bostic et al., 1990).

The iterative procedure used five choices on average. If the interval in which the indifference value fell became less than a month the process stopped. At the end of the bisection process, the program asked subjects to confirm their choice. If so, they moved on to the next elicitation. If not, the process for that elicitation started anew. In the analyses, we used the indifference value for which subjects confirmed their choice.

We randomized the order of the risk and the ambiguity parts. When a subject had completed the first part, the interviewer would point out the differences with the next part of the experiment before proceeding. Within the risk and ambiguity parts, we randomized the order of the second (the elicitation of the utility for gains) and the third stage (the elicitation of the utility for losses). The first stage always had to come first, because it produced the inputs for the second and third stages. The fourth stage always came last because it required information from the second and third stages. Within the fourth stage we also randomized whether the gain or the loss part came first.

To test for consistency and to obtain insight into the quality of the data, we included two types of repetitions. First, we repeated the third iteration of the bisection process in twelve tasks. In the third iteration, most subjects were close to indifference and, hence, this was a rather strong test of consistency. Second, at the end of the second stage, the elicitation of the gain sequence, we repeated the elicitation of x_3^+ , both in the risk and in the ambiguity part.

4.3. Analyses

Utility curvature

We used two different methods to investigate utility curvature, one non-parametric, the other parametric. The non-parametric method calculated the area under the utility function. The domain of U was normalized to $[0,1]$ by transforming every gain x_j^+ to x_j^+/x_5^+ and every loss x_j^- to x_j^-/x_5^- . If utility is linear, the area under the normalized curve equals $1/2$. For gains, utility is convex (concave) if the area under the curve is smaller (larger) than $1/2$. For losses, utility is convex (concave) if the area under the curve is larger (smaller) than $1/2$.

In the parametric method, we estimated the utility function by the power family, the most commonly employed parametric family (Wakker, 2008). The power family is defined by x^α with $\alpha > 0$. For gains [losses] $\alpha > 1$ corresponds to convex [concave] utility, $\alpha = 1$ corresponds to linear utility, and $\alpha < 1$ corresponds to concave [convex] utility. Estimation was done by nonlinear least squares. As the results from the parametric estimation were similar to those of the nonparametric analysis, we will concentrate on the nonparametric results. The parametric results are reported in the online appendix.

Loss aversion

To measure loss aversion we used Kahneman and Tversky's (1979) definitions of loss aversion. They defined loss aversion as $-U(-x) > U(x)$ for all $x > 0$. This definition reflects that losses loom larger than gains as the absolute utility of any loss exceeds the utility of the commensurate gain. To measure loss aversion coefficients, we computed

$-U(-x_j^+)/U(x_j^+)$ and $-U(-x_j^-)/U(x_j^-)$ for $j = 1, \dots, 5$, whenever possible.⁶ When $U(-x_j^+)$ and $U(-x_j^-)$ could not be observed directly, we estimated them through linear extrapolation using the elements of the elicited sequence $\{x_5^-, \dots, x_1^-, x_0, x_1^+, \dots, x_5^+\}$. A subject was classified as loss averse if $-U(-x)/U(x) > 1$ for all observations, as loss neutral if $-U(-x)/U(x) = 1$ for all observations, and as gain seeking if $-U(-x)/U(x) < 1$ for all observations. To account for response error, we also used a more lenient rule, which classified subjects as loss averse, loss neutral, or gain seeking if the above held for more than half of the observations.

To test for robustness we also used definition of loss aversion according to which a decision maker is loss averse if the kink of utility at the reference point exceeds 1. They define an index of loss aversion as $U'_\uparrow(0)/U'_\downarrow(0)$, where $U'_\uparrow(0)$ represents the left derivative and $U'_\downarrow(0)$ represents the right derivative of U at the reference point. In our method this definition is measured by the ratio $x_1^+/-x_1^-$, which requires no interpolation of utility. A subject was classified as loss averse if this ratio exceeded one, as loss neutral if it was equal to one, and as gain seeking if it was smaller than one. Statistical testing confirmed that the loss aversion coefficients were the same under this definition as under the definition of Kahneman and Tversky (1979) and, consequently, all conclusions were the same (see the online appendix for details).

Probability weighting and event weighting

To measure probability and event weighting requires knowledge of $U(x_p^+)$, $U(x_p^-)$,

⁶ To be able to compute these $-x_j^+$ had to be contained in $[x_5^-, 0]$ and $-x_j^-$ had to be contained in $[0, x_5^+]$.

$U(x_E^+), U(x_E^-)$ for $p = 0.1, 0.3, 0.5, 0.7, 0.9$ and $E = [0, .2], [.1, .5], [.3, .7], [.5, .9], [.8, 1]$.

We used linear interpolation to measure these utilities. To compare our results with those from the literature, we also performed a parametric estimation of the probability weighting function using Prelec's (1998) two-parameter specification $w^i(p) = \exp\{-\delta^i(-\ln p)^{\gamma^i}\}$, $i = +, -$. The δ -parameter controls for pessimism with higher values corresponding with less pessimism. The γ -parameter corresponds with sensitivity to changes in likelihood with higher values corresponding with higher sensitivity. Estimation was by nonlinear least squares. To test for robustness we also used the neo-additive weighting function of Chateauneuf et al. (2007). This analysis gave the same results and is reported in the online appendix.

An important question that we seek to address is whether utility and event weighting are the same for risk and ambiguity. Hence, our main interest is to test for equalities of subjective parameters. Classic significance tests are less suitable for this as they do not allow to state evidence for the null and they overstate the evidence against the null (Rouder et al., 2009). Hence, we used Bayesian statistics and Bayes factors instead. Bayes factors indicate how much more likely the alternative is than the null. For example, a Bayes factor of 10 indicates that the alternative is 10 times as likely as the null given the data. A Bayes factor of 0.10 indicates that the null is 10 times as likely as the alternative given the data. We used the common interpretation that a Bayes factor larger than 3 signals some support for the alternative over the null, a Bayes factor larger than 10 signals strong support for the alternative over the null, and a Bayes factor larger than 30 signals very strong support for the alternative over the null. Similarly, a Bayes factor less than 0.33 signals some support for the null over the alternative, a Bayes factor less than 0.10 signals strong support for the null over the alternative, and a Bayes factor less than 0.03 signals very strong support for the null over the alternative. To

check for robustness and because the Bayesian t -test is sensitive to the variance of the underlying distributions we also performed classic nonparametric tests. These generally led to the same conclusions (unless otherwise stated) and are reported in the online appendix.

5. Results

5.1. Consistency checks

Subjects made the same choice in 76% of the repetitions of the third iteration of the bisection process. This is better than the reversal rates around $\frac{1}{3}$ which are commonly observed in the literature (Stott, 2006), especially if we take into account that subjects were close to indifference in the third iteration. A Bayesian Anova showed support for the null that consistency was the same for risk and ambiguity and for gains and losses ($BF = 0.21$).

Figure 2: Original and repeated elicitation of x_3^+

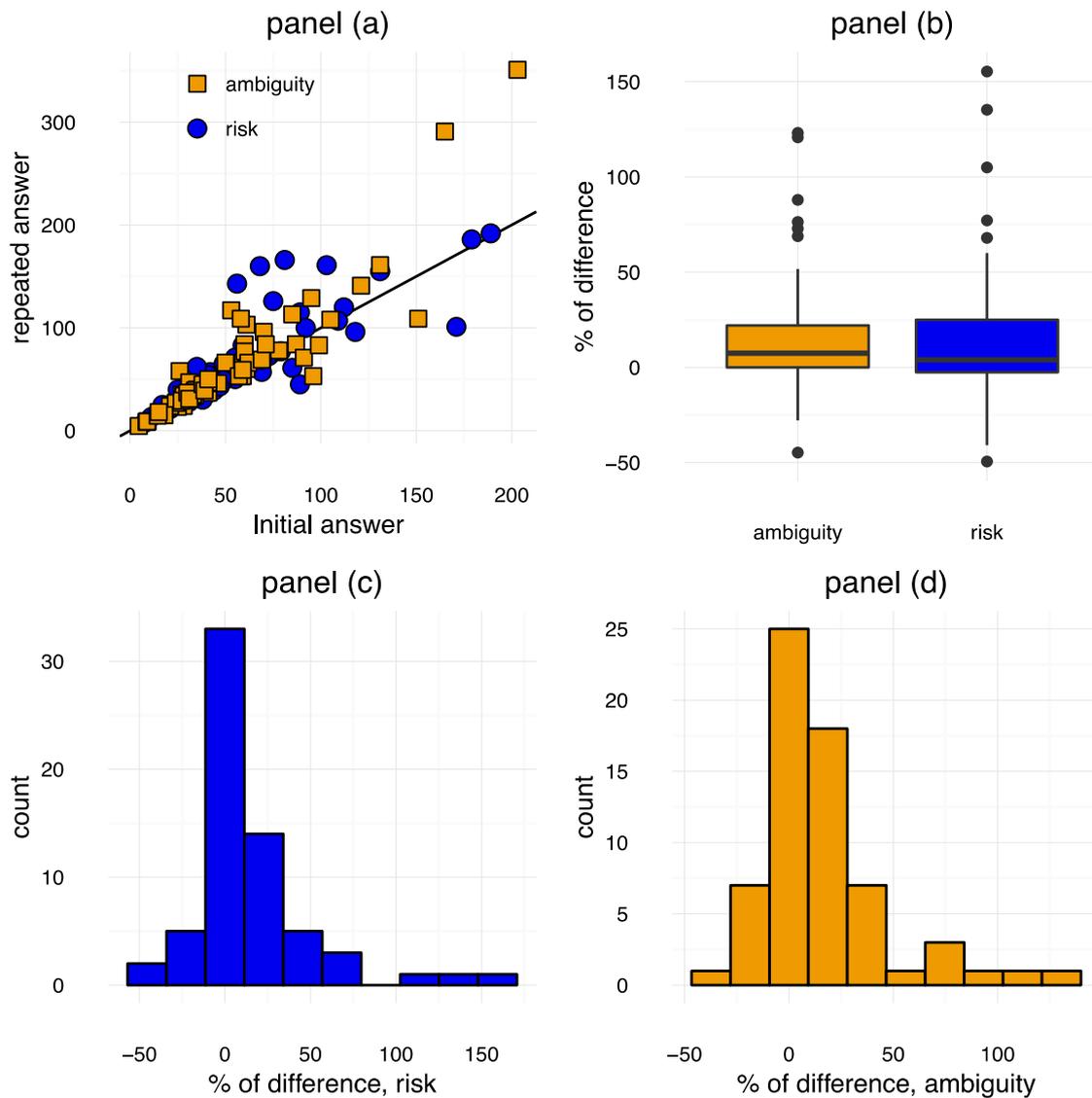
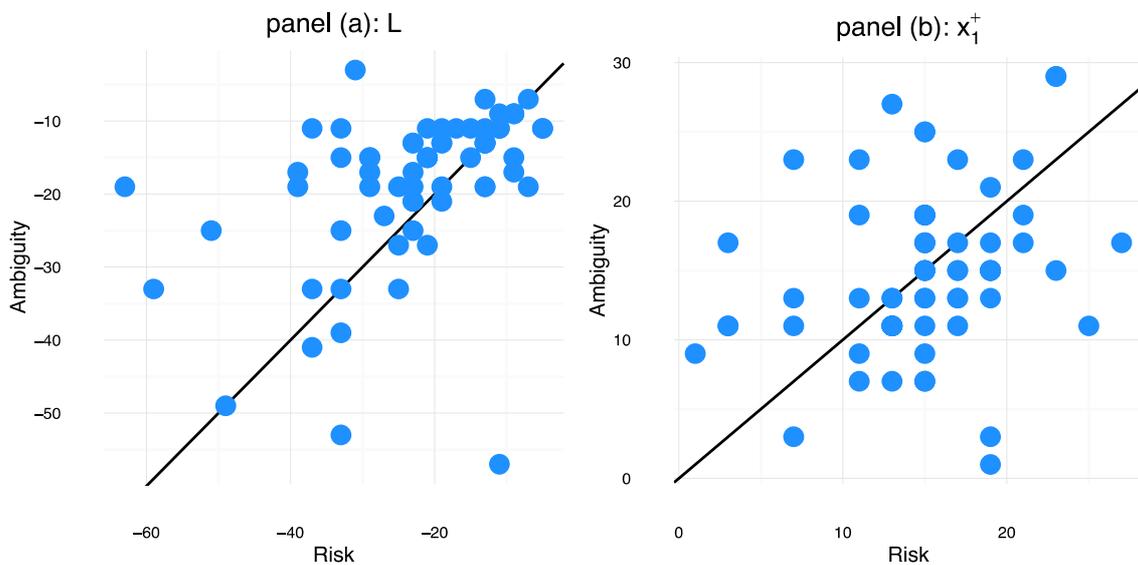


Figure 2 shows the results of the original and the repeated elicitation of x_3^+ . Panel (a) shows that the two elicitation were closely related except for a few outliers. The correlation was almost perfect. For risk, the Spearman rank correlation was 0.92, for ambiguity it was 0.93. Panel (b) shows that the difference between the original and the repeated elicitation as a percentage of the original elicitation was centered around zero. Panel (c) shows a histogram for the % difference for risk, and Panel (d) for ambiguity. These panels show a slight tendency for higher values in the repeated elicitation. For risk, a Bayesian analysis was inconclusive ($BF = 1.25$). For ambiguity, we found some support that the original and the repeated elicitation indeed differed ($BF = 4.34$).

5.2. Ambiguity aversion

Ambiguity aversion means that subjects prefer decisions under risk to decisions under ambiguity when the objective and subjective probability are the same. The first two choices of the first stage of our measurement method allows two tests of ambiguity aversion. In the first choice ambiguity aversion predicts that $L_a > L_r$ where the subscripts a and r stand for ambiguity and risk, respectively.⁷ In the second choice, ambiguity aversion predicts that $x_{1,r}^+ > x_{1,a}^+$.⁸

Figure 3: Tests of ambiguity aversion



⁷ By ambiguity aversion $G_p L > G_E L$ for any G and L if the subjective probability of event E is equal to p . Thus $0 \sim G_p L_r > G_E L_r$ and thus $0 \sim G_E L_a > G_E L_r$, which implies $L_a > L_r$.

⁸ By ambiguity aversion $G_p 0 > G_E 0$ and, thus, $x_{1,r}^+ \sim G_p 0 > G_E 0 \sim x_{1,a}^+$.

Panel (a) of Figure 3 shows the relation between L_r and L_a . The figure shows that most values of L_a were above the diagonal consistent with ambiguity aversion. Statistical testing indeed showed support for the hypothesis that $L_a > L_r$ over the null that $L_a = L_r$ ($BF = 2.92, p < 0.01$ in a Wilcoxon test). However, panel (b) of Figure 3, which displays the relation between $x_{1,r}^+$ and $x_{1,a}^+$ shows less evidence for ambiguity aversion. Ambiguity aversion would in this figure predict that points lie below the diagonal, but there was no obvious pattern. Indeed, the data supported the null that $x_{1,r}^+ = x_{1,a}^+$ i.e. ambiguity neutrality, over the alternative of ambiguity aversion ($BF = 0.14$).

Table 2: Classification of subjects in terms of ambiguity attitude

		Gains (x_r^+)			
		averse	neutral	seeking	
Mixed (L)	averse	19	5	11	35
	neutral	6	1	7	14
	seeking	8	1	7	16
		33	7	25	65

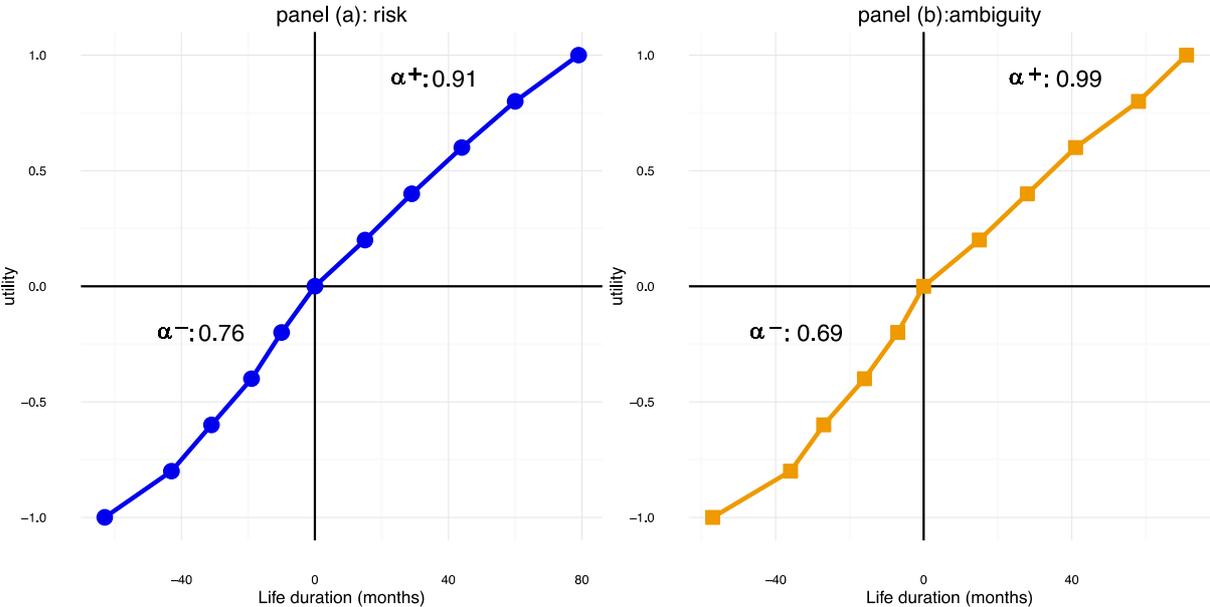
Table 2 shows the classification of the subjects. The table shows that ambiguity aversion was the most common pattern in both tests. For mixed prospects, we found support for ambiguity aversion ($BF = 8.14$). For gain prospects the test was inconclusive ($BF = 0.51$).

5.3 The utility for gains and losses

Figure 4 shows the utility for gains and losses under risk (Panel (a)) and ambiguity

(Panel (b)) based on the median data. Two things are noteworthy. First, the utility functions under risk and ambiguity look similar and, second, they are consistent with the typical finding of convex utility for losses and concave utility for gains. For ambiguity, utility was close to linear for gains. Moreover, utility was more curved for losses than for gains. For money, most studies found the opposite pattern. The figure also shows the estimated power coefficients based on the median data.

Figure 4: The utility for gains and losses based on the median data



Moving to the individual data, Figure 5 shows the relation between the area measures between risk and ambiguity (Panel (a)) and between gains and losses (Panel (b)). Panel (a) shows that there was no clear difference in the shape of utility between risk and ambiguity. Indeed, a Bayesian Anova supported the null that utility was the same for risk and ambiguity ($BF = 0.14$). Panel (b) shows that most points were above the diagonal signaling more curvature for losses than for gains. A Bayesian Anova showed some

support for the hypothesis that utility was different for gains and losses ($BF = 2.89$).⁹

Figure 5: Individual shapes of utility

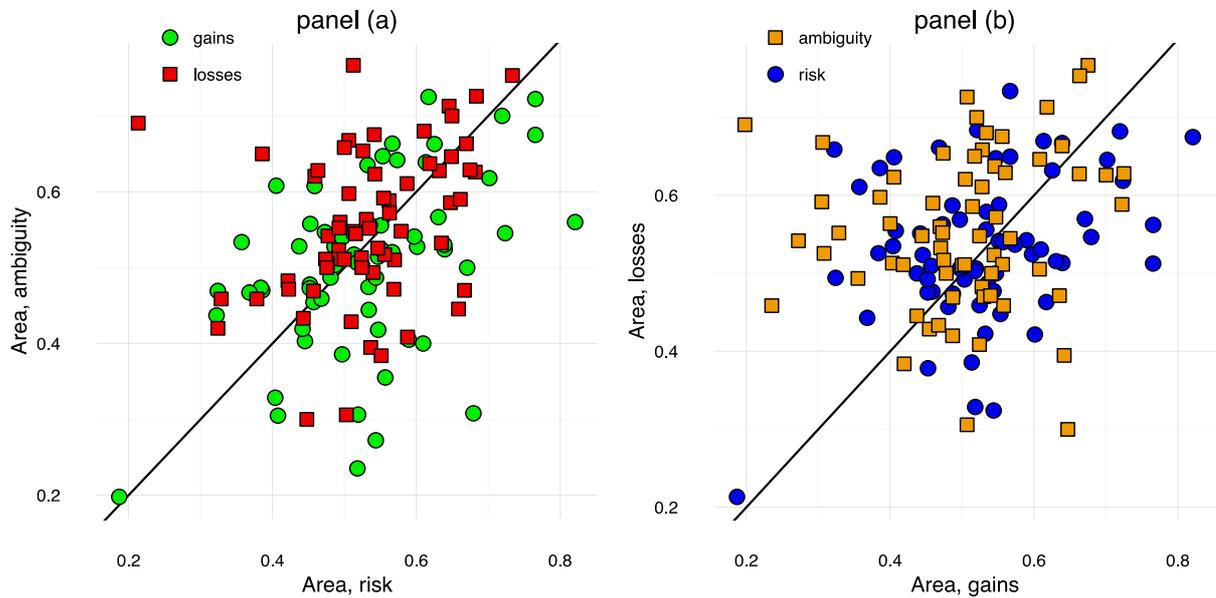
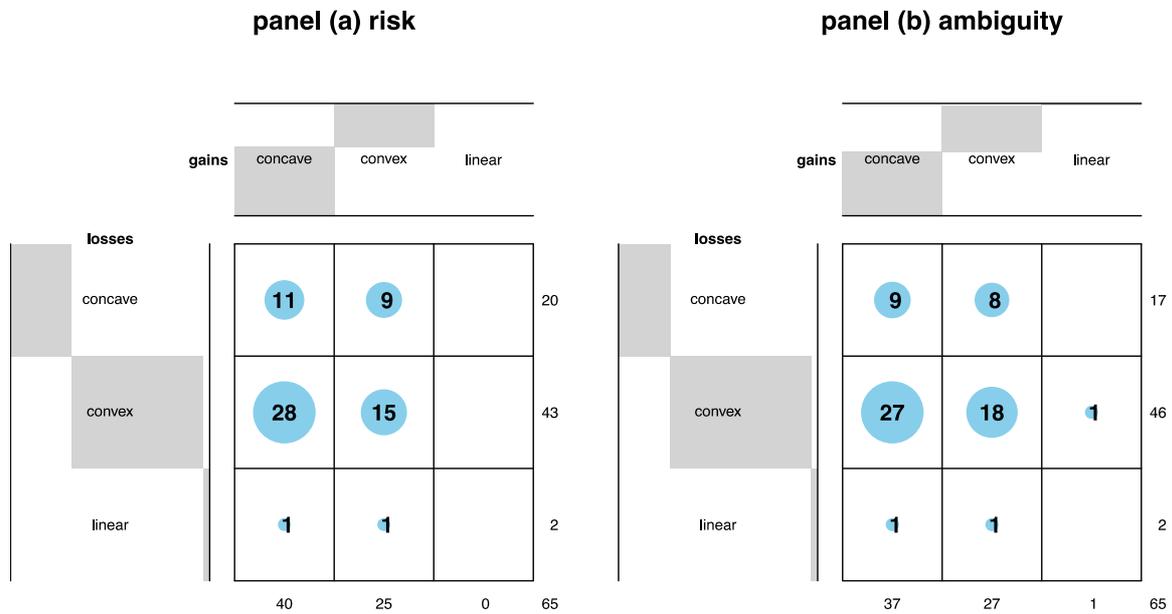


Table 3 shows the classification of subjects according to the shape of their utility function. Panel A gives the results for risk, Panel B those for ambiguity. The table confirms the impressions obtained above. The classification was similar for risk and ambiguity and the common pattern was S-shaped utility: concave for gains and convex for losses. However, while statistical tests showed support for the hypothesis that utility was convex for losses ($BF = 5.67$ for risk, $BF = 370.22$ for ambiguity), we found no evidence that utility was concave for gains. The data were inconclusive as to the concavity of utility for risk ($BF = 0.95$) and they supported the null of linearity for ambiguity ($BF = 0.14$). Only a small minority of the subjects behaved according to the traditional assumption in decision theory that utility under risk is concave throughout. In fact, there were more subjects with everywhere convex utility. The parametric results confirmed that utility was the same for risk and ambiguity, but they showed less of a difference in utility

⁹ $p = 0.03$ by a standard Anova.

curvature between gains and losses. They are reported in the online appendix.

Table 3: Classification of subjects by the shape of their utility function



5.4 Loss Aversion

The previous subsection showed little differences in utility curvature between risk and ambiguity. Consequently, to explain the ambiguity aversion that we observed for mixed prospects by differences in utility as the SDU class of ambiguity models does, loss aversion should differ between risk and ambiguity. We will now explore whether it did.

Figure 6: The relation between median gains and median losses with the same absolute utility

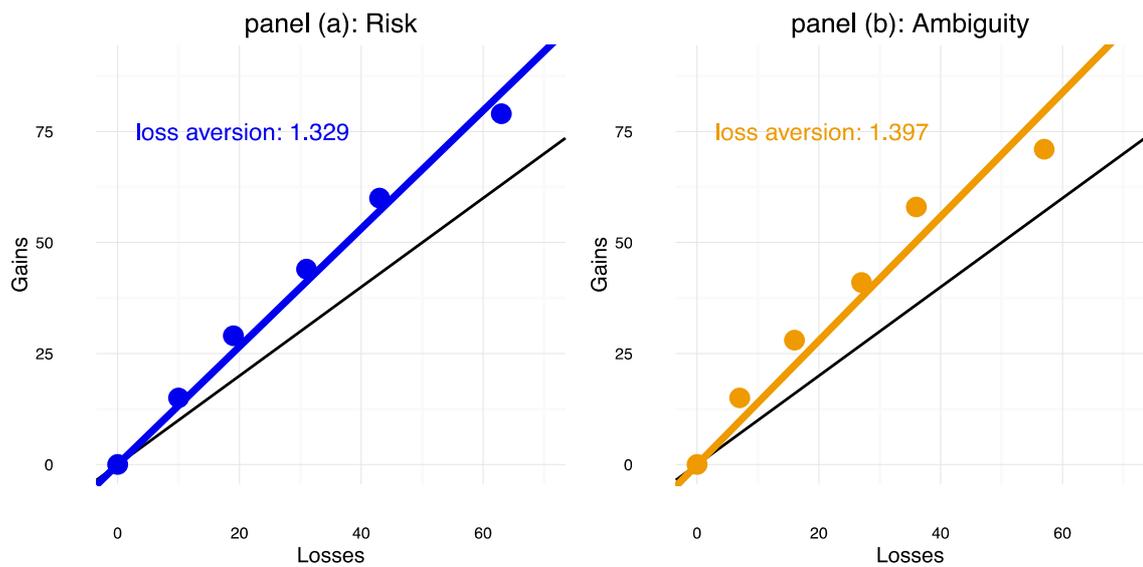
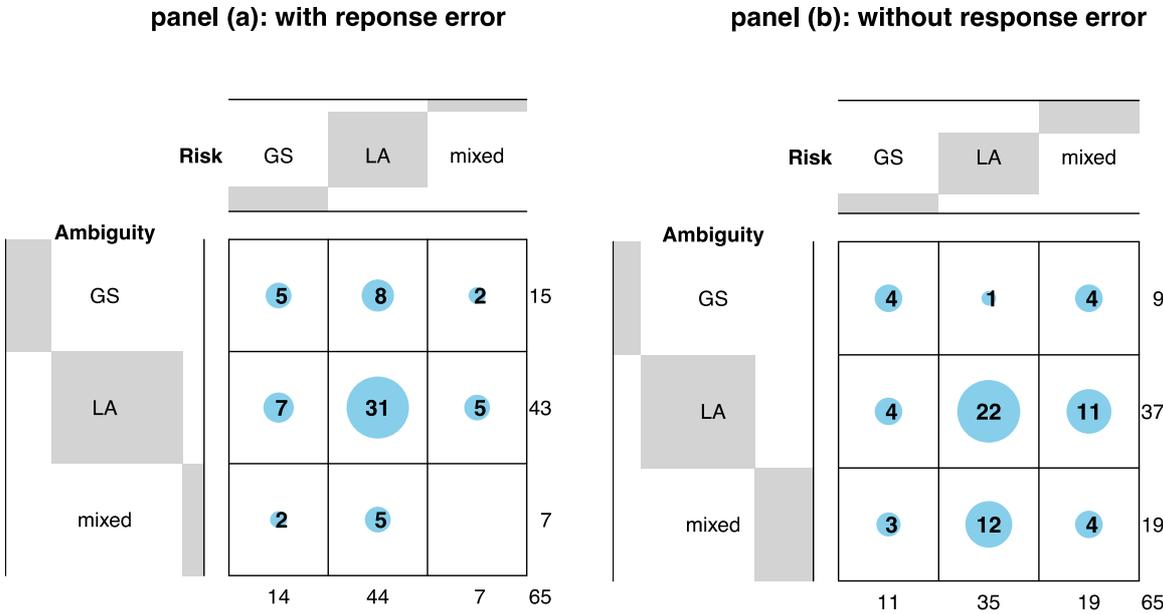


Figure 6 displays the relations between the medians of x_j^+ and $-x_j^-$ under risk and under ambiguity. Consistent with Kahneman and Tversky's (1979) definition of loss aversion, $-x_j^-$ was always lower than x_j^+ (for all j) for both risk and ambiguity. We obtain an aggregate measure of loss aversion by regressing the x_j^+ on $(-x_j^-)$ in each panel. Figure 6 displays the coefficients from these regressions. The coefficients were close for risk and ambiguity. At the aggregate level loss aversion was moderate and somewhat lower than what has typically been found for money.

Moving to the individual level, a Bayesian Anova showed strong support for the null that the ratios $x_j^+ / -x_j^-$ were the same for risk and ambiguity ($BF = 0.09$). We also found very strong support that they were constant across tasks ($BF = 0.00$). The medians of the individual ratios varied between 1.45 and 1.92 for risk and between 1.50 and 1.75 for ambiguity. These values are comparable to the loss aversion coefficients found by Bleichrodt et al. (2007) for health. They are higher than those found by Attema et al. (2013).

Table 4 shows the classification of the subjects in terms of loss aversion based on Kahneman and Tversky’s (1979) measure. There was clear evidence of loss aversion regardless of whether we accounted for response error. We found very strong evidence that there were more loss averse than gain seeking subjects (both $BF > 174.1$). The median loss aversion coefficients were 1.45 for risk and 1.57 for ambiguity. We found support for the hypothesis that they differed from 1, the case of loss neutrality ($BF = 13.02$ for risk and $BF = 7.39$ for ambiguity). We also found support for the null that loss aversion was the same for risk and ambiguity ($BF = 0.14$) signaling that loss aversion could not explain the ambiguity aversion for mixed prospects that we observed.

Table 4: Individual classification in terms of loss aversion for risk and ambiguity

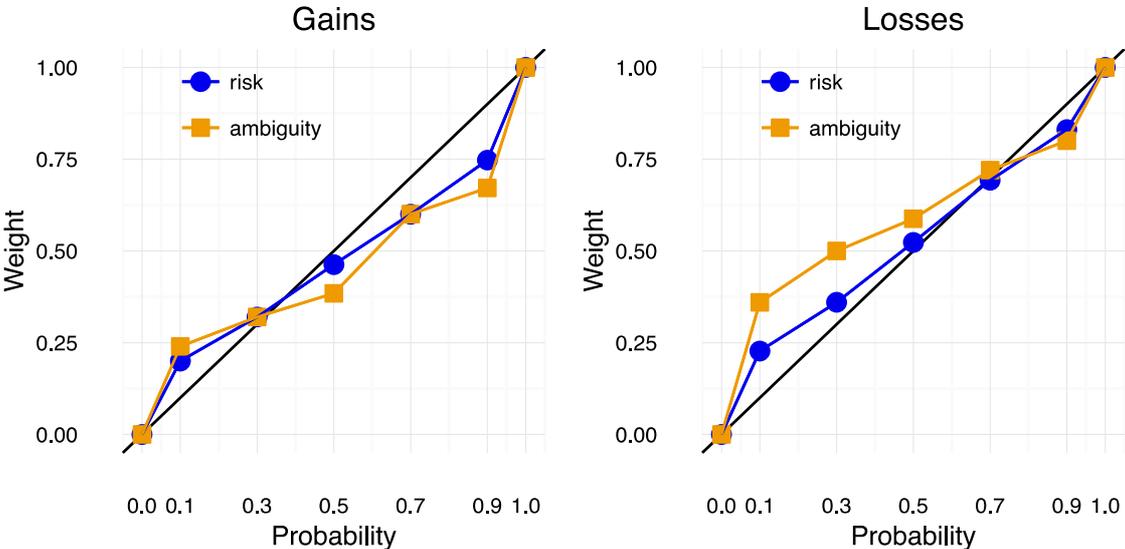


5.5. Probability weighting and event weighting

Figure 7 shows the probability and event weighting functions for gains and losses based on the median data. Recall that the class of source-dependent weighting ambiguity models explain ambiguity aversion by a difference between probability and event weighting.

For gains, the probability weighting and event weighting functions were similar except perhaps for probability 0.5. This is consistent with the absence of ambiguity aversion for gains that we observed. However, for losses the event weighting function was more elevated than the probability weighting function for probabilities smaller than 0.75, which implies ambiguity aversion for losses. Identical probability and event weighting for gains, but higher event weighting than probability weighting for losses (in combination with the same utility curvature and loss aversion for risk and ambiguity that we observed above) can indeed explain the ambiguity aversion for mixed prospects that we observed.

Figure 7: Probability and event weighting functions for gains and losses based on the median data



A Bayesian Anova showed very strong evidence that probability and event weighting depended on the domain (gains versus losses) and support for the hypothesis that the interaction between domain and context (risk versus ambiguity) mattered ($BF = 7.02$). This is consistent with our above observations that probability and event weighting were similar for gains but differed for losses. Looking at the separate probabilities for gains, we found support for the null that probability weighting and event weighting of 0.1, 0.3, and 0.7 were the same (all $BF < 0.19$), whereas for probabilities 0.5 and 0.9 the evidence was inconclusive. For losses, we found very strong support for the hypothesis that the probability and event weight of 0.1 differed ($BF = 45.14$) and support that they differed for probability 0.3 ($BF = 4.12$). For probability 0.5 the evidence was inconclusive ($BF = 0.93$) and for probabilities 0.7 and 0.9 we found support for the null that the probability and event weight were the same (both $BF < 0.20$).

Both the probability weighting and the event weighting functions had an inverse S-shape, as commonly observed in empirical research (Fox and Poldrack 2014). This shape implies that unlikely events are overweighted and that more likely events are underweighted. We found very strong evidence that probability 0.1 was overweighted and that probability 0.9 was underweighted for both risk and ambiguity and for both gains and losses (all $BF > 69295$). For gains, we also found very strong evidence that probability 0.7 was underweighted (both $BF > 6811$). For losses, we found very strong evidence that probability 0.3 was overweighted (both $BF > 93.8$).

For the other cases the results depended on the context and on the domain. For risk and gains, we found support that probability 0.3 was overweighted ($BF = 6.11$) and for the null that there was no probability weighting of probability 0.5 ($BF = 0.30$). The

probability weighting for gains was comparable with Bleichrodt and Pinto (2000) who also found overweighting of probabilities less than 0.5, no probability weighting for probability 0.5 and underweighting of probabilities exceeding 0.5. For risk and losses, we also found support for the null of no weighting of probability 0.5 ($BF = 0.21$), but inconclusive evidence about the weighting of probability 0.7 ($BF = 1.14$).

For ambiguity and gains, the evidence was inconclusive regarding the weighting of probability 0.3 ($BF = 2.13$), but we found very strong evidence for the underweighting of probability 0.5 ($BF = 42.5$). For ambiguity and losses, we found very strong evidence that probability 0.5 was overweighted ($BF = 32.4$) and support for the null of no weighting of probability 0.7 ($BF = 0.28$).

As we mentioned above, the Bayesian Anova showed that the weights differed between gains and losses. For risk, we found evidence that the weights of probabilities 0.7 and 0.9 differed (both $BF > 4.95$). For probabilities 0.1 and 0.3 we found support for the null of no difference (both $BF < 0.15$), and for probability 0.5 the evidence was inconclusive ($BF = 0.46$). For ambiguity, we found very strong support that the weighting of probabilities 0.5, 0.7, and 0.9 differed between gains and losses (all $BF > 32.86$), support that the weighting of probability differed for probability 0.3 ($BF = 8.05$) and inconclusive evidence for probability 0.1 ($BF = 1.28$).

The medians of the individual estimates of the Prelec (1998) two-parameter probability weighting function were $\gamma^+ = 0.46$ and $\delta^+ = 1.04$ for risk and gains, $\gamma^+ = 0.39$ and $\delta^+ = 0.95$ for ambiguity and gains, $\gamma^- = 0.64$ and $\delta^- = 0.85$ for risk and losses and $\gamma^- = 0.54$ and $\delta^- = 0.66$ for ambiguity and losses. The estimates for gains and risk are very close to the ones observed by Bleichrodt and Pinto (2000) for health. The difference in event weighting between risk and ambiguity was due to a difference in the parameter δ^- , reflecting pessimism ($BF = 5.46$). For the other parameters (γ^+ , γ^- ,

and δ^+) we found support for the null that they were the same for risk and ambiguity (all $BF < .33$). Wakker (2010) has argued that likelihood insensitivity reflects the cognitive component of event weighting and pessimism the motivational component. Our data suggest that ambiguity aversion for mixed health prospects is caused by motivational factors.

6. Discussion

We have shown how ambiguity preferences for health can be completely measured. We started with a general model that includes many of the ambiguity models that have been proposed in the literature as special cases. We showed how the different parameters of this general model (utility, loss aversion, and event weighting) could be measured. This made it possible to gain insight into the question to what extent we can use insights from the rich literature on health decision under risk to inform health decisions under ambiguity where evidence is thin on the ground. In addition, we could explore the descriptive validity of ambiguity models for health.

Our data also suggest that many of the results that have been derived for health decision making under risk may carry over to ambiguity. We found support that utility, loss aversion, and event weighting for gains are the same between risk and ambiguity. The only difference was observed for event weighting for losses. Consequently, results derived under risk and involving only gains may prove to be useful in predicting preferences under ambiguity.

The difference between probability weights and event weights for losses could explain the ambiguity aversion for mixed prospects that we observed. The absence of

differences in utility, event weighting and loss aversion for health gains is consistent with the observed absence of ambiguity aversion for health gains. The absence of ambiguity aversion for health gains may be surprising. On the other hand, evidence from money also suggests that ambiguity aversion may not always be the dominant pattern (e.g. Binmore et al., 2012; Charness et al., 2013). Our findings suggest that the effects of ambiguity will be most pronounced for losses. Our study included no direct tests of ambiguity aversion for health losses and an interesting topic for future research would be to explore that prediction in detail.

Regarding the descriptive validity of ambiguity models, our data provide support for models such as prospect theory that capture ambiguity aversion through a difference between probability and event weights. For the smooth ambiguity model, which is increasingly used in health economics, our data suggest that the φ -function which captures ambiguity attitude, is close to linear.

We made several assumptions throughout our analysis. The assumption of biseparable preferences seems reasonable. As mentioned above, biseparable preferences are very general and the data of Abdellaoui et al. (2016) support the general assumption underlying biseparable preferences for money. A crucial assumption is that subjects take 50 years as their reference point. We induced this reference-dependent thinking by coding all outcomes as gains and losses from 50 years. The results of Attema et al. (2013) provide support for our way of inducing subjects to adopt this reference point, but it would be very desirable to know more about the reference point that subjects adopt in experiments about health.

We followed Curley et al. (1984) by implementing ambiguity through the specification of ranges of possible probabilities. Baillon et al. (2012) call this imprecise

ambiguity. Another possibility is to introduce experts who give conflicting probability judgments. Baillon et al. (2012) called this conflicting ambiguity and they showed that it can give different results compared to imprecise ambiguity. Yet another possibility would be to introduce events for which no probability information is given at all and to measure the subjects' beliefs about these events for example using the method of Baillon (2008).

Another possible extension would be to use a different reference point than 50 years, as we did. Arguably, 50 years is quite high and perhaps subjects' ambiguity preferences would change if the induced reference point would be less than 50 years. On the other hand, a reference points of 50 years does not deviate too much from subjects' actual life-expectancy and this may have made it easier for them to adopt. Lower reference points might not be perceived as neutral but as a loss and, thus, in those cases our method for inducing the reference point might be less successful.

7. Conclusion

Many medical decisions involve ambiguity. Empirical research suggests that people are not neutral towards ambiguity, but health economics research has typically ignored ambiguity attitudes. We assumed a general model of ambiguity preferences and measured its different components for risk and ambiguity. For health gains we found no differences in utility and event weighting between risk and ambiguity suggesting that in this domain we can use the rich literature on health decision making for risk to inform health decision making under ambiguity. For health losses, however, we found a difference in event weighting between risk and ambiguity. Utility was the same. Loss

aversion was also the same between risk and ambiguity. Taken together our data provide support for models such as prospect theory that explain ambiguity attitudes through a difference in event weighting. Utility was convex for losses and linear to concave for gains. Event weighting was inverse S-shaped reflecting the overweighting of unlikely events and the underweighting of more likely events. Finally, we found support for loss aversion with health losses weighting about 1.5 times as much as health gains.

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