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# Medium-term public transit route ridership forecasting: what, how and why? A case study in Lyon 

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#### Abstract

Demand forecasting is an essential task in many industries and the transportation sector is no exception. This is because accurate forecasts are a fundamental aspect of any rationale planning process and an essential component of intelligent transportation systems. In the context of public transit, forecasts are needed to support different level of planning and organisational processes. Short-term forecast, typically a few hours in the future, are developed to support real-time operations. Long-term forecast, typically 5 years or more in the future, are essential for strategic planning. Those two forecast horizons have been widely studied by the academic community but surprisingly little research deal with forecast between those two ranges. The objective of this paper is therefore twofold. First, we proposed a generic modelling approach to forecast next 365 days ridership in a public transit network at different levels of spatiotemporal aggregation. Second, we illustrate how such models can assist public transit operators and transit agencies in monitoring ridership and supporting recurrent tactical planning tasks. The proposed formulation is based on a multiplicative decomposition that combines tree-based models with trend forecasting. The evaluation of models on unseen data proves that this approach generates coherent forecast. Different use cases are then depicted. They demonstrate that the resulting forecast can support various recurrent tactical tasks such as setting future goals, monitoring ridership or supporting the definition of service provision. Overall, this study contributes to the growing literature on the use of automated data collection. It confirms that more sophisticated statistical methods can help to improve public transportation planning and enhance data-driven decision making.


Keywords: Public transit, Ridership forecasting, Machine Learning, Smart Card Data, Transport planning

## Highlights

- Examines the need for medium-term forecasting in public transit systems
- Proposes an operational modelling framework to forecast ridership one year ahead at different levels of spatiotemporal aggregation
- Outlines different applications of the forecasts for tactical planning and ridership monitoring
- Exploitation of archived passive data can enhance data-driven decision making


## ${ }_{37}$ Author statement:

${ }_{38}$ Oscar Egu: Conceptualization, Methodology, Formal analysis, Data Curation, Writing - Original 39 Draft, Visualization, Investigation. Patrick Bonnel: Supervision, Validation, Writing - Review 40 and Editing.

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# Medium-term public transit route ridership forecasting: what, how and why ? A case study in Lyon 

Word Count: 7400


#### Abstract

Demand forecasting is an essential task in many industries and the transportation sector is no exception. This is because accurate forecasts are a fundamental aspect of any rationale planning process and an essential component of intelligent transportation systems. In the context of public transit, forecasts are needed to support different level of planning and organisational processes. Short-term forecast, typically a few hours in the future, are developed to support real-time operations. Long-term forecast, typically 5 years or more in the future, are essential for strategic planning. Those two forecast horizons have been widely studied by the academic community but surprisingly little research deal with forecast between those two ranges. The objective of this paper is therefore twofold. First, we proposed a generic modelling approach to forecast next 365 days ridership in a public transit network at different levels of spatiotemporal aggregation. Second, we illustrate how such models can assist public transit operators and transit agencies in monitoring ridership and supporting recurrent tactical planning tasks. The proposed formulation is based on a multiplicative decomposition that combines tree-based models with trend forecasting. The evaluation of models on unseen data proves that this approach generates coherent forecast. Different use cases are then depicted. They demonstrate that the resulting forecast can support various recurrent tactical tasks such as setting future goals, monitoring ridership or supporting the definition of service provision. Overall, this study contributes to the growing literature on the use of automated data collection. It confirms that more sophisticated statistical methods can help to improve public transportation planning and enhance data-driven decision making.


Keywords: Public transit, Ridership forecasting, Machine Learning, Smart Card Data, Transport planning

## 1 Introduction

Demand forecasting is an essential task in many industries and the transportation sector is no exception. In fact, accurate prediction of future demand is an essential components of intelligent transportation systems [Vlahogianni et al., 2014, Koutsopoulos et al., 2019] and a fundamental aspect of any rationale planning process [Bonnel, 2002, Ortúzar and Willumsen, 2011]. Thus, it is not surprising that passenger demand forecasting is a widely studied subject. To summarize this area of research, we must take into account the domain of application and the type of planning issues the forecast intend to address. In many organisations including public transport, they are three commonly accepted level of planning and organisational control [van de Velde, 1999, Pelletier et al., 2011, Ortúzar and Willumsen, 2011]. Strategic level deal with long-term decisions and objectives. Tactical level focus on decisions that take place in the medium-term and aims to guarantee that the means to reach long-term goals are in place. Operational planning is concerned with short-term decisions that ensure the efficiency of the production. In agreement with this hierarchical order of decision-making activities, operators and transport agencies must generate different forecasts.

Short-term forecasting is a very active field [Vlahogianni et al., 2014] that deal with models that predict demand from few minutes to few hours into the future [Vlahogianni et al., 2014, Noursalehi et al., 2018]. The wide adoptions of smart card fare collection systems has provided new opportunities for short-term forecasting. Zhai et al. [2018] have discussed the literature about short-term bus passenger flow forecasting models and methods. Ma et al. [2014] proposes an Interactive Multiple Model-based Pattern Hybrid approach and evaluate it using empirical smart card data collected along one bus route over one year in Jinan, China. Ding et al. [2016] forecast short term subway ridership using gradient boosting decision trees. Using Beijing smart card data, Li et al. [2017] proposes a novel multiscale radial basis function to forecast the irregular fluctuation of subway passenger flows under special events. Using smart card data from London Underground, Noursalehi et al. [2018] proposed to predict short term passenger arrivals at transit stations using state-space models and considering station interactions. In the context of public transit (PT), authors argue that short-term forecasting can enable the design of better control strategies and improve passenger experience by proactively adjust services and customer information [Koutsopoulos et al., 2019, Noursalehi et al., 2018, Ma et al., 2014, Wei and Chen, 2012]. While appealing and surely helpful, short-term forecasting can be hard to implement in real-life settings because it requires real-time data, continuous actualization of the model and trust in the model output. Short-term forecasts are also developed to support near real-time operational decision making. However, PT systems cannot always react efficiently in real-time due to limited flexibility in resources (e.g vehicles, staff) and infrastructure constraints. Transport services and infrastructures are thus often designed and planned years in advance.

Long-term ridership forecasting deals with models that predict demand for time horizon ranging from 5 to 15 years ahead. In contrast to short-term forecasting, it is often a one-time exercise and forecasts are rarely generated continuously. Forecasts are produced to assess and evaluate future scenarios and support long-range strategical planning. The most common method for long-term ridership forecasting traditionally relies on four-step travel demand model [Boyle, 2006, Ortúzar and Willumsen, 2011, Bonnel, 2002]. Those models are data-intensive as they incorporate many elements such as land use, future population, choice model, network description etc. On one hand, it is a strength as this type of model can be used to forecast structural changes such as the introduction of a new route but also to evaluate different policy choice [Ortúzar and Willumsen, 2011, Bonnel, 2002]. On the other hand, it is a weakness because the resulting model can be costly, complex and hard to modify. Consequently, other forecasting approaches have been developed. For example, change in ridership in response to change in services or fares can be forecast using elasticity
coefficient [Boyle, 2006, Totten and Levinson, 2016, Paulley et al., 2006]. Other approaches include, spatial regression method [Pulugurtha and Agurla, 2012], rules of thumb method based on similar routes or professional judgement [Boyle, 2006, Diab et al., 2019]. In practice, those models and approaches are often calibrated for a limited set of situation such as an average weekday, a typical peak hour etc. They are, therefore, difficult to use in recurrent monitoring of the demand and cannot support tactical and operational planning activities.

Surprisingly, little research deal with forecast between those two horizons i.e medium-term forecasting. However, those kinds of forecasts are part of the toolbox needed for the effective planning of public transit systems. They can be of great use for PT operators and agencies that want not only to be able to adapt real-time operation (short-term forecasting) and evaluate strategic plan (long-term forecasting) but also to monitor tactically and continuously the evolution of demand. Toqué et al. [2017] have recently proposed to use machine learning models to predict PT ridership one year ahead in a disaggregate and continuous manner. However, the authors didn't introduce in their analysis a multiyear trend component neither a description of the level of supply although they may surely be needed for medium-term forecasting. Moreover, they barely discuss the practical aspect of the forecasting framework and motivate their work with use cases. This paper seeks to address these research gaps and has two complementary objectives:

1. To develop a generic forecasting approach that combined passenger flow trend analysis with machine learning model to predict one year in advance, at different levels of spatiotemporal aggregation, ridership volume in a PT network.The model should consider seasonal effects, holiday period, bank holiday, day of the week, hours of the day and unusual effect to forecast not only an average ridership one year in advance, but the variability of ridership across days, hours and network elements.
2. To illustrate how such forecasts can support tactical planning tasks and assist PT operators and agencies in monitoring ridership. The illustrations are based on real use cases from Lyon public transit network.

To this end, the paper has been organized in the following way. It begins with a presentation of the modelling approach. After that, relevant data are identified, prepared and described. Then, the forecasts are validated using unseen data and a bottom-up approach. Finally, use cases are provided to illustrate the value of such data-driven framework. Results show that the proposed modelling approach is valid. Transit agencies can leverage the resulting forecast to better monitor and anticipate ridership in their network. Overall, this study contributes to the growing literature on the use of automated data collection to improve public transportation planning. Findings confirm that more sophisticated statistical methods can facilitate analysis that used to rely primarily on professional judgement [Hanft et al., 2016, Pelletier et al., 2011, Koutsopoulos et al., 2019].

## 2 Modelling framework

Let's denote $Y_{i}=\left(y_{i, 1}, \ldots, y_{i, t}, \ldots, y_{i, n}\right)$ as the vector of observed ridership volume on element $i$ of a PT network for each time step $t \in 1, ., . ., n$. Let's denote $X_{i, t}$ the set of features (explanatory variables) whose values are known for $t \in 1, ., . ., m$ where $m(m>n)$ is the prediction horizon. Our goal is to estimate a regression model $f_{i}($.$) for each element i$ such that $y_{i, t}=f_{i}\left(X_{i, t}\right)+\varepsilon$ where $\varepsilon$ is the difference between the observed value and the predicted value $\widehat{y_{i, t}}=f_{i}\left(X_{i, t}\right)$. This formulation described a typical univariate regression problem where (1) each element of the network $i$ is considered independent of the rest of the network, (2) each observation $y_{i, t}$ is considered independent of the other's observations.

As proposed by Toqué et al. [2017], to estimate $f_{i}($.$) we can use machine learning models such$ as ensemble of decision trees. Those models have recently gained much popularities in various fields due to their ability to learn complex non-linear relation between features and provide higher accuracy than single machine learning models [Friedman et al., 2001, Opitz and Maclin, 1999]. Those models combine several decision trees into one single model that output the mean of all decision tree. A single decision tree can be seen as a stratification of the ridership volume into some simple regions using a set of splitting rules based on the available features. The underlying principle of those models is that by combining single decision trees we can significantly improve the predictive performance and reduce the variance of a single tree [Friedman et al., 2001, Breiman, 2001, Friedman, 2001].

To learn a set of decision trees effectively the two most common algorithms are random forest (RF) and gradient boosting (GB). Random forest was introduced by Breiman [2001] and is based on the concept of bagging. More precisely, each decision tree is built independently on a random subset of the training data but also considering only a random sample of features at each split. In doing so, the algorithm enforces diversity in the trees which when we average them may reduce the variance of the model [Breiman, 2001]. Gradient boosting trees were formalized by Friedman [2001] and differ from the random forest model in the sense that decision trees are built sequentially using strategically resample training data. More specifically, each new tree is built to recover the errors resulting from the model obtained with the ensemble of trees produced at the previous steps. In this approach, each of the decision trees can remain rather small with performance slightly above random guess. Fitting them sequentially can then help to improve the model in areas of the feature space that were missed by previous ensemble [Friedman et al., 2001].

One aspect of those machine learning models is that they assume independence between the $y_{i, t}$ and thus can't learn time-dependent structure and forecast potential trend. In fact, as explained above the model output are computed by averaging decision trees which are themselves based on historical ridership data. However, ridership volume may have statistical properties that evolve through time and might also be view as a non-stationary time series. To deal with this aspect, we can assume that ridership volume has two components a yearly trend-cycle component $s_{i, T}$ and a yearly adjusted component $a_{i, t}$. Ridership level can then be expressed using multiplicative decomposition:

$$
\begin{equation*}
y_{i, t}=s_{i, T} \times a_{i, t} \tag{1}
\end{equation*}
$$

were $s_{i, T}$ denotes the mean of $y_{i, t}$ in year $T, t \in T$ and $a_{i, t}$ is the yearly adjusted level ridership of element $i$ at time step $t$.

The forecasting task can then be divided into two subtasks were we have to forecast $s_{i, T}$ and $a_{i, t}$. The rationale behind this process is twofold. First, $a_{i, t}$ is assumed to be stationary and free of trend and thus can be estimated with ensemble of decision trees $\left(\widehat{a_{i, t}}=f_{i}\left(X_{i, t}\right)\right.$ ). Second, $s_{i, T}$ is supposed to be non-stationary and evolve slowly over time and can be forecast by taking the last value of the yearly trend-cycle component multiply by a growth factor $\alpha_{i}$. $\widehat{y_{i, t}}$ can then be obtained in the following way:

$$
\begin{equation*}
\widehat{y_{i, t}}=\widehat{a_{i, t}} \times\left(1+\alpha_{i}\right) s_{i, T-1} \tag{2}
\end{equation*}
$$

In other words, the forecasted ridership for element $i$ is equal to the mean ridership of the previous year $s_{i, T-1}$ multiply by a growth factor while the deviation from the mean yearly ridership volume $a_{i, t}$ is predicted using a regression model. $\alpha_{i}$ can then be estimated using a weighting average of the observed historical year-mean percentage evolution:

$$
\begin{equation*}
\alpha_{i}=\frac{\sum_{T=2}^{N} w_{T} \frac{s_{i, T}}{s_{i, T-1}}}{\sum_{T=2}^{N} w_{T}} \tag{3}
\end{equation*}
$$

where $N$ is the number of years used to train the model and $w_{T}=1 /(N+1-T)$ is the weight associated with year $T$ defined with inverse time decay function. This weighted formulation is proposed to estimate $\alpha_{i}$ from multiyear behaviour of each element while giving higher weight to more recent years.

This forecasting formulation is well suited to our objectives for two reasons. First, it exploits the property of ensemble models to learn the influence of various features on detrended ridership data. Second, it aligned forecast with previous year observed ridership volume of element $i$ to ensure coherency of the forecast with the most recent element state. This formulation can be seen as a conservative continuation of previous year's ridership mean volume combined with a model that learns historical behaviour of the network element under different conditions of the features space. As noted by Hyndman and Athanasopoulos [2018], traditional time series models (such as seasonal ARIMA) don't allow irregular events and have difficulty to accommodate multiple imbricated seasonality. The intuition behind the above formulation is that the decision tree model is able to capture those effects while remaining robust to potential outliers.

At this step, we have now a modelling approach that can be used to forecast the future ridership volume at time step $t$ of each element $i$ denoted as base forecast. To establish forecast for higher levels of the network hierarchy such as a group of elements $J$ (e.g group of stops, group of routes) or larger temporal aggregation (e.g day, week, month, working day), we can employ the simple and straightforward bottom-up approach. In this case, the forecasted ridership volume of higher hierarchies element $J$ for the period $M=[t 1, \ldots, t 2]$ denoted $\widehat{R_{J, M}}$ is obtained by summing the different base forecast:

$$
\begin{equation*}
\widehat{R_{J, M}}=\sum_{i \in J} \sum_{t=t 1}^{t 2} \widehat{y_{i, t}} \tag{4}
\end{equation*}
$$

This approach is a classical way to deal with time-series collections that naturally presents hierarchical properties and different seasonal pattern [Hyndman and Athanasopoulos, 2018, Kahn, 1998]. It has the advantage to preserve in the forecasting task the dynamic and characteristics of individual elements while making it possible for the analyst to obtain forecast at the desired spatiotemporal level of the PT network.

## 3 Data preparation and exploration

Since the introduction of automated data collection systems, it is now possible to access highresolution ridership data. Those new data sources have the potential to change the current state of practice in ridership forecasting if they are accurate and of good quality [Boyle, 2006, Diab et al., 2019]. To be used in medium-term forecasting those data need also to be correctly curated and archived so there are enough observations to train models. The proposed modelling approach requires the definition of a base forecast level. This level should not be too noisy to ensure models can properly learn patterns and at the same time sufficiently detailed for most of the required tactical analysis. This level should also be set from the perspective of the organisation managing the network which can be different from the passenger perspective. We suggest that the most appropriate spatiotemporal base level of aggregation for medium-term forecasting are:

- Temporal aggregation $(t)$ : hourly data because it is needed to account for intra-day variation and define supply level accordingly. However, it should be noted that the same methodology could be applied to daily data if this resolution level is deemed sufficient.
- Spatial aggregation $(i)$ : route level is most suitable than stop level because supply level is more than anything else link to route elements.

In Lyon, the current fare transaction system is an entry only system that was introduced in 2002. Passenger can validate using either smart card or magnetic paper. Validation is mandatory when boarding a bus or tramway and when entering the subway network. All transactions are then anonymized and stored with timestamp and localisation attributes. For this research, the fare transactions from 2014 to 2018 for the subway network ( 4 metro lines and 2 funicular lines), the tramway network ( 5 lines) and high-frequency buses known as line C ( 25 lines) were extracted from the Lyon PT operator data warehouse. A map of the extracted network is given in figure 1. Those routes were selected because they represent more than $80 \%$ of the total ridership of the network. This sample was also deemed to be enough to evaluate correctly our approach. Fare transactions were then summed by route and by hour ${ }^{1}$. To ensure, the completeness of the data, the following procedure was implemented recursively for each route:

- Generate the hourly time bin from the 1st of January 2014 00:00 to the 31st December 2018 23:00.
- Lookup for the number of fare transactions summed by hour. If no transaction is found for a given hour it was assumed that no passenger board the route and the ridership value was set to zero. This procedure is put in place to ensure the consistency of the training data which must contain periods with and without ridership to correctly learn the route historical behaviour ${ }^{2}$.

For the rest of this paper, the dataset resulting from the above procedure will be referred to as the route ridership volume and will form the base level of our modelling framework.

Our modelling framework also required a set of features that may explain the route ridership volume variations while being available one year in advance. It is well recognized that PT ridership presents multiple temporal seasonalities and regular cycles that can be encoded with ordinary calendar attributes. Consequently, a calendar features table common for all routes was manually crafted. Features of this spreadsheet are described in table 1. Ridership is also influenced by the level of supply i.e the quantity of service produced. One of the most common and simple indicator to describe this aspect of transit is the number of commercial kilometres offered. This indicator was thus extracted from the operator data warehouse and choose as an explanatory variable. Unfortunately, for this research, this feature was available with enough historical depth only at the level of day and route. Noted also that in Lyon, commercial kilometres offered by routes are set one year in advance by the operator planning team for contractual and financial reasons. Thus, like calendar features, they can be determined sufficiently in advance and be used as predictors in medium-term forecasting (which is not the case of potential other features such as weather or unplanned events).

The calendar table, the supply feature and routes ridership volumes were then merged. To explore the characteristics of the resulting dataset we have aggregated the ridership volume of the 36 selected routes and perform exploratory visualizations in figure 2. In figure 2a, it can be seen that there are cyclical patterns that repeat every year such as a strong decrease of ridership volume during summer months (July and August). There are also long-term dynamics in the ridership volume with an observable increasing tendency. This is because Lyon network has been gaining popularities in the last few years. In figure 2 c , the variation of daily ridership volume for the year 2018 are observed more finely. This figure indicated that they are multiple imbricated seasonalities and calendar effects. More precisely, it can be seen that school holiday periods (e.g in February, April, October and December) but also other events such as bank holidays or special

[^0]

Figure 1: Map of the study network, source: prepared by the authors

| Features | Description |
| :--- | :--- |
| Hour | 24 categories |
| Month | 12 categories |
| Week number | Numeric from 1 to 53 |
| Day of the week | 7 categories |
| School holiday | 7 categories, one for each holiday period |
| Public holiday | 14 categories, one for each French public holiday |
| Adjacent to public holiday | Binaries if weekdays and adjacent to public holiday |
| Light and music festivals | Binaries if major citywide events |

Table 1: Hand crafted calendar features, source: prepared by the authors
events have an impact on the ridership volume. Similarly, we observe a strong decrease in ridership during weekends and summer months. As indicated by figure 2 a , those seasonalities seems to be recurrent every year but calendar effects are moving in time because each year events and holidays can fall in different days of the year. In figure 2 b , the relation between the total daily number of commercial kilometres produced and the ridership volume is depicted. This figure shows that there are three main states in the network that correspond to three typical planned service output

## 4 Models fitting and forecast errors

| Name | Model | Features | Decomposition |
| :--- | :--- | :--- | :---: |
| HM | Historical median | Hour, Type of day, Month, Working day |  |
| HMT | Historical median | Hour, Type of day, Month, Working day | x |
| RF | Random forest | Calendar features | x |
| RFT | Random forest | Calendar features | x |
| RFTS | Random forest | Calendar features and supply feature |  |
| GB | Gradient boosting | Calendar features | x |
| GBT | Gradient boosting | Calendar features | x |
| GBTS | Gradient boosting | Calendar features and supply feature |  |

Table 2: List of implemented models, source: prepared by the authors

In the previous sections, we have defined the problem, proposed a modelling framework, gather the data and perform some preliminary exploratory analysis, we now present models fit. Table 2, depicts the list of models that we have decided to evaluate. The first model formulation is a naive historical approach. In this case, the forecast is computed using the median of all past time step over the historical observation with the same characteristic as the forecasted time step. Time step characteristics were in this case defined with the cartesian product between the hour, the month, the type of day (weekday, Saturday, Sunday) and a boolean indicator for working day (no public holiday, no school holiday, no special events). This formulation will serve as the baseline to evaluate the two ensemble models described in section 2 . Table 2 also indicates if the models were




$\begin{array}{ll}\text { (a) Dayli ridership volume from } 2014 \text { to } 2018 \text {, red curve correspond to } & \text { (b) Relation between the supply feature and the daily ridership volume, } \\ 30 \text { days moving average } & \text { points are colored by day type }\end{array}$


## 

80
(c) Calendar heatmap of daily ridership volume in 2018 (d) Hourly ridership volume from the 7th of May 2018 to the 20th of
Figure 2: Exploration plot based on the aggregated ridership volume of the 36 selected routes, source: prepared by the authors
trained with the raw ridership volume or with the decomposed ridership volume. In the second case, the equation 2 was used to forecast future ridership volume.

The accuracy of a forecast procedure can only be truly determined using data that were not used to fit the model [Hyndman and Athanasopoulos, 2018]. To do so, there are two common approaches: the cross-validation where several sets of tests are sequentially constructed and the hold-out approach where the data is divided into two portions. In this research, the hold-out approach was selected. The data was thus divided between a training set comprising all observations from 2014 to 2017 and a test set consisting of 2018 observations. To measure forecast errors the following standard metrics were chosen:

$$
\begin{equation*}
\mathrm{MAE}=\frac{1}{n} \sum_{i=1}^{n}\left|y_{i, t}-\widehat{y_{i, t}}\right| \tag{5}
\end{equation*}
$$

$$
\begin{equation*}
\operatorname{MAPEv}=\frac{1}{n} \sum_{i=1}^{n} \frac{\left|y_{i, t}-\widehat{y_{i, t}}\right|}{y_{i, t}}, \forall y_{i, t}>v \tag{6}
\end{equation*}
$$

$$
\begin{equation*}
\operatorname{MdAPE}=\operatorname{median}\left(\frac{\left|y_{i, t}-\widehat{y_{i, t}}\right|}{y_{i, t}}\right) \tag{7}
\end{equation*}
$$

In table 3, we have reported the error measures on the train and test dataset for different levels of aggregations. First, as expected, when the aggregation level increases, errors decrease significantly. For instance, the best model at the base forecast has a MdAPE of $11.7 \%$ almost four times bigger than the best model MdAPE once forecasts are aggregated by day ( $2.8 \%$ ). This indicates that the base levels are challenging to forecast but the bottom-up approach allows to generate coherent results. In other words, base forecast errors tend to compensate when forecasts are aggregated by route or by time. A second important observation is that ensemble models outperform baseline model in terms of absolute errors (MAE) but also in terms of percentage errors (MAPEv and MdAPE). Ensemble models consider a more complex feature space but still can generalize to previously unseen data more comprehensively and without overfitting. However, there are no important differences in terms of accuracy between the gradient boosting and the random forest which is not surprising since both methods have strong similarities. What is also clear from this table is that the decomposition approach is essential when historical data with a certain depth is used to model future ridership. This is because the decomposition ensures the coherency of the forecast with the most recent observed ridership volume. Finally, the introduction of supply feature in ensemble models can reduce the errors especially large errors. If we compare the RFT (random forest with decomposition) and RFTS (random forest with decomposition and supply feature), it can be seen that median absolute percentage errors are quite similar but mean absolute percentage error can be considerably higher when the supply feature is omitted. This is because, when there is a significant reduction in the kilometres produced the model based on calendar features will assume no change in the ridership volume.

## 5 Use case analysis

In the previous section, we have fitted different models and generate forecasts of ridership volume one year in advance. We have shown that it was possible to obtain rather low errors at higher aggregated levels but the forecast quality decreases at lower levels of aggregation. While forecast accuracy is in itself an important matter it is also important to recall that PT networks are complex systems that are impacted by all sort of unexpected and exogenous events. Therefore, the above models should not be seen solely for their prediction capability but also for their ability to assist PT

|  |  | TRAIN SET (2014-2017) |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | HM | HMT | RF | RFT | RFTS | GB | GBT | GBTS |
| Base level (route-hour) | MAE | 97 | 93 | 79 | 74 | 69 | 81 | 77 | 67 |
|  | MAPE_50 (\%) | 17,4 | 16,8 | 15,1 | 14,5 | 12,9 | 16,6 | 16,1 | 13,4 |
|  | MdAPE (\%) | 10,5 | 10,0 | 10,3 | 9,6 | 9,0 | 10,7 | 10,1 | 9,1 |
| Aggregated (route-day) | MAE | 1795 | 1670 | 1236 | 1063 | 712 | 1230 | 1088 | 859 |
|  | MAPE (\%) | 25,6 | 24,8 | 11,2 | 10,3 | 5,5 | 13,1 | 12,1 | 8,2 |
|  | MdAPE (\%) | 6,3 | 5,6 | 5,2 | 4,3 | 3,0 | 5,4 | 4,6 | 3,8 |
| Aggregated (hour) | MAE | 2682 | 2618 | 1913 | 1816 | 1741 | 2040 | 1987 | 1564 |
|  | MAPE (\%) | 16,0 | 15,7 | 17,1 | 16,9 | 18,0 | 20,2 | 20,1 | 14,8 |
|  | MdAPE (\%) | 6,4 | 6,0 | 5,5 | 5,0 | 5,0 | 6,4 | 6,2 | 4,9 |
| Aggregated (day) | MAE | 51725 | 49869 | 30793 | 26737 | 18264 | 31063 | 28508 | 21007 |
|  | MAPE (\%) | 67,0 | 67,1 | 14,7 | 14,1 | 6,3 | 18,5 | 18,4 | 11,5 |
|  | MdAPE (\%) | 4,4 | 4,0 | 3,1 | 2,4 | 1,8 | 3,3 | 2,8 | 2,2 |
|  |  | TEST SET (2018) |  |  |  |  |  |  |  |
|  |  | HM | HMT | RF | RFT | RFTS | GB | GBT | GBTS |
| Base level (route-hour) |  | 131 | 115 | 118 | 99 | 95 | 123 | 104 | 93 |
|  | MAPE_50 (\%) | 21,7 | 21,7 | 19,9 | 19,8 | 17,2 | 21,1 | 21,4 | 17,4 |
|  | MdAPE (\%) | 14,5 | 12,8 | 13,7 | 11,9 | 11,7 | 14,4 | 12,6 | 11,7 |
| Aggregated (route-day) | MAE | 2662 | 2157 | 2339 | 1708 | 1480 | 2351 | 1720 | 1497 |
|  | MAPE (\%) | 36,3 | 36,9 | 26,8 | 26,7 | 16,6 | 28,1 | 27,8 | 17,7 |
|  | MdAPE (\%) | 10,7 | 7,7 | 9,9 | 6,8 | 6,4 | 10,0 | 6,9 | 6,5 |
| Aggregated (hour) | MAE | 3562 | 2878 | 2993 | 2140 | 2182 | 3226 | 2349 | 1976 |
|  | MAPE (\%) | 25,7 | 24,9 | 19,7 | 19,1 | 16,7 | 25,4 | 25,1 | 16,4 |
|  | MdAPE (\%) | 10,0 | 7,1 | 8,4 | 5,7 | 5,9 | 9,7 | 6,8 | 5,8 |
| Aggregated (day) | MAE | 75721 | 54068 | 63457 | 33658 | 31259 | 63643 | 35738 | 30671 |
|  | MAPE (\%) | 55,2 | 55,7 | 28,9 | 26,7 | 9,0 | 32,9 | 31,0 | 13,8 |
|  | MdAPE (\%) | 8,1 | 4,4 | 7,2 | 2,8 | 3,1 | 7,8 | 3,5 | 3,1 |

Table 3: Model results on the train and test dataset for different level of aggregation (HM: historical median, RF: random forest, GB: gradient boosting, T indicates the use of the proposed decomposition approach, $S$ indicates the incorporation of supply feature), source: prepared by the authors
organisations in monitoring ridership and in improving tactical decision-making activities. This is what we intend to demonstrate in this section by introducing a few use cases.

With the above modelling approach, it is possible to obtain coherent aggregated ridership forecasts. These types of forecasts could be used for tactical decision making. For instance, they can assist senior executives in setting next year goals and monitoring their PT network with a more data-driven approach. Similarly, every year, transit agencies need to prepared next year budget which obviously requires at one point some sort of ridership forecast. In practice, this process can be tedious and is often a matter of expert. In the case where different operators coexist in the same network, this task is even more complex and critical for the proper functioning and financing of the system. Agencies could use the proposed approach to generate forecasts for all route and then aggregated them to prepare budgets that match more closely the future variation of ridership and fit the financial/operational division of the network ${ }^{3}$. To illustrate this first use case, the weekly forecast for the two random forest models obtained through decomposition (RFT and RFTS) by type of transportation mode is plotted in figure 3.

In figure 3, it can be seen that the different series are overall quite close and the aggregation of

[^1]

Figure 3: Weekly forecast one year in advance for the three transportation mode (RFT: decomposed random forest, RFTS: decompose random forest with supply features, Y: real ridership volume), source: prepared by the authors
models captures typical calendar patterns such as the impact of school holidays, public holidays, or citywide events (i.e peak at week 50 for subway network). It can also be seen that the ridership volume of high-frequency bus network has increased more quickly than anticipated by the two models, especially after September. Finally, figure 3 indicates that for the tramway routes both model yield different forecast. This is because in 2018 the tramway network was impacted by important construction work of a new tramway route (T6) that leads to change in the service provision. Those type of elements can be further inspected by an analyst using models outputs in a retrospective manner. Especially, models can be used to identify routes whose behaviour deviate from historical behaviour as captured by the models. In doing so, analysts could identify and prioritize which route they need to review first in a more efficient manner than doing it based on "anecdotal knowledge" or fixed cycle [Coleman et al., 2018]. In figure 4, we have plotted each route as a point in a two-dimension space where the x-axis is the annual percentage error between the RFTS model and the real 2018 ridership and the y-axis is the total real ridership volume. Using figure 4 it is easy to identify routes that require further analysis, balancing the importance of the route ( y -axis) and the importance of the deviation from the model (x-axis). Figure 4 indicates that most routes errors are under $5 \%$ but some route exhibit higher discrepancies between model and real observations such as C3, C14, C15, C9 or T5. This route level analysis can be further extended to go deeper into the available data. For instance, real and model route ridership volume were aggregated by month and inspected in figure 5 .

In figure 5, we can observe that there is indeed a large diversity of route ridership historical pattern. For instance, route C3 is the busiest bus route in Lyon and important road work were carry on between mid-2016 to mid-2019 to provide exclusive right-of-way. The route was divided into two sections and part of the stops were relocated. As indicated by figure 5 , it had a great impact on the 2017 ridership volume and the model forecast further decreased of the demand in 2018. However, by the end of 2018 , as the route progressively returns to better operational condition, the ridership starts to increase significantly in an unforeseen manner for the model. In 2016, a strong decrease of ridership is observed on route $\mathrm{C} 14^{4}$ follow by a return at historical ridership volume during 2017. These disruptions were not well assimilated by the models, and

[^2]

Figure 4: Annual ridership volume forecast error for decomposed random forest with supply feature model (RFTS), source: prepared by the authors
further growth of the route was forecast. As mentioned earlier, in 2018 the tramway network was impacted by the construction of a new tramway line (T6). In figure 4, it can be seen that while tramway routes T1 and T3 are forecast correctly the model underestimates/overestimates the traffic on routes T2/T4. Figure 5 indicates that those routes exhibit a strong decrease in summer month (July/August). Models with supply feature partially anticipate this decrease (see figure 5 and figure 3) but models with only calendar features couldn't predict those changes (see figure 3). The impacts of those kinds of exogenous elements are in practice very difficult to understand and measure clearly without confronting the real ridership with a "business as usual" scenario. With the above modelling approach, transit agencies can now more easily do so. They can monitor route ridership with a data-driven approach using a predictive model that is easy to re-actualize but also to implement. Moreover, they can use these "business as usual" forecast to estimate in advance the number of trips impacted by a planned disruption. Once the period of disruption and the routes impacted are known, an analyst can interrogate models to retrieve the forecasted number of impacted trips. This information can then be used in the design of replacement services or mitigation plan. In a similar vein, if different periods of disruption are being considered, models could also be used to identify the period that minimizes the impacted volume of trips. For this kind of use case, one may prefer to leverage on model using calendar features so the forecast is a pure "business as usual" prediction.

The above use cases were based on spatial and/or temporal aggregation of model outputs but the base model i.e by route and hour can also be of value to apprehend in-depth ridership pattern. To this aim, forecasts need to be synthesized in such a way that the information can directly be helpful for tactical planning purposes. One way to do so would be to cluster the model output to identify a set of typical daily ridership profiles. Spherical kmean is a popular text mining prototype-based clustering algorithm [Buchta et al., 2012]. It relies on the cosine distance to measure dissimilarity between objects which has interesting properties for our problem as the observations are cluster

| C14 |
| :---: |
| "wryry |
| C2 |
|  |
| C26 |
| $\text { why } x^{d y} \sqrt{m y}$ |
| C8 |
| whymy mh wos |
| MC |
|  |
| T5 |
| rumpmasta |


$\frac{C 13}{0.4}{ }_{0.3}$







U











Figure 5: Monthly time series of ridership volume by route (RFTS train: training of decomposed random forest with supply feature (2014-2017), RFTS test: testing of decomposed random forest with supply feature (2018), Y: real monthly ridership by route), source: prepared by the authors
irrespectively of their magnitude i.e the ridership volume. It can be mathematically express as a minimization of the cosine distance of all possible allocation of objects $m$ to clusters $c(m) \in 1, \ldots, k$ and over all prototypes $p_{1}, \ldots, p_{k}$ in the same feature space as object $m$ denoted $x_{m}$ :

$$
\begin{equation*}
\min \quad \sum_{m} 1-\frac{x_{m} \cdot p_{c(m)}}{\left\|x_{m}\right\| \cdot\left\|p_{c(m)}\right\|} \tag{8}
\end{equation*}
$$

In our problem, the observation $x_{m}$ is the vector of hourly forecasted route ridership volume on a given day. The features space dimension is 24 and the number of observations is equal to the number of days ahead we forecast multiply by the number of routes ${ }^{5}$. In prototype-based clustering, the number of clusters $k$ need to be defined first. Then, a fixed-point algorithm can iterate between optimal allocation of observations to cluster and optimal prototypes to attempt to determine a partition that minimizes equation 8 . For the sake of illustration, we have decided to retain 8 clusters accounting for almost $80 \%$ of the dissimilarity. The fixed-point algorithm was then run 20 times and the best solution was retained. The resulting clusters prototypes are given in figure 6a and were named according to their shape: bell shape clusters (BP) from 1 to 4 are daily ridership profiles that don't exhibit two peak periods while peak profiles clusters (PP) numbered from 1 to 4 are daily ridership profiles that exhibit a morning and evening peak pattern.


Figure 6: Clustering analysis of model forecast, source: prepared by the authors
Those 8 clusters synthesize the high-resolution data contained in the base model. They facilitate the analysis and provide more manageable information to transportation planners and analysts. They can be used to further explore the future demand of each route. A typical use case would be to produce in addition to the previous analysis on the ridership volume a calendar of future daily ridership profile. The output of this procedure is given in figure 6 b for three selected routes (bus route C8, subway route MA and tramway route T3). In this figure, it can be seen that the models have learned differents daily ridership profiles for each route. For instance, bus route C8 is characterized by a change from prototype PP3 to prototype PP4 during holiday weekdays. It means that the model forecast that during school holidays the peak period will be less important with regard to the daily volume. Moreover, the model has learned that a typical Saturday will exhibit a BP3 profile while Sunday will exhibit a higher concentration of trip in the morning (prototype BP2). Subway route A daily profiles are overall more stable. Unlike route C8, Saturday and Sunday

[^3]prototype are equal. During weekday the assigned prototype remains the same (PP1) except during the month of august (PP4). Finally, the tramway route T3 is characterized by weekday with a high concentration of trip during morning peaks periods (prototype PP2). Compared to the subway route the weekend prototype is BP3 meaning that in proportion less ridership is forecasted in the late evening. These observations demonstrate that the models have learned and forecast distinct daily ridership profiles. Once cluster those forecasts can be examined more easily and help analysts to adjust service plans to intra-day demand variation. Altogether, this use case section offers some insights into how the proposed modelling framework could be used in real-world applications and answer common tactical issues. One of the main advantages of the proposed solution is the flexibility to explore forecasts at different levels of aggregation.

## 6 Conclusions

This research was undertaken with two objectives. First, to design a modelling framework suitable for medium-term forecasting of route ridership volume. Second to evaluate the potential benefit of such forecasts for transit agencies and operators. The proposed model can identify trends in ridership over the past years in order to consider them for forecasting. It is also able to consider variability within each year due to seasonal effects, holiday, bank holiday, weekday effects and hour of the day. Finally, the proposed model can consider measures of supply evolution over time for each PT route. The evaluation of different models has shown that the proposed decomposition formulation can learn complex patterns from historical data that can then be satisfactorily projected into the future. The resulting forecasts have proven to be quite appropriate to facilitate recurrent tactical decision making and help planning better services. The use case section outlined different applications to demonstrate the potential of such a modelling approach for tactical planning to support PT operator or authority needs. Examples of applications include setting future goals, monitoring ridership volume at different levels of aggregations, estimating the impact of future disruptions and supporting the definition of future service provision. It is therefore recommended that transit agencies complement their traditional reporting tools with these types of predictive approaches. By doing so, they can value at their full potential their historical data and enhance data-driven decision making. Moreover, the cost of implementation of such a tool is reduced and not too challenging. Models should simply be trained automatically by batch (e.g. every month) based on the above data preparation procedure. Then the provision of modern dashboarding tools with drill-down capability will make the data available through a web application for anyone interested in the organisation.

Although the study has demonstrated that the proposed modelling formulation generate coherent forecasts and is operational, it also has several limitations that need to be considered and further investigated. First, the ensemble models are trained using the same weight for all historical observations. Even though this approach is simple and generic it would be interesting to elaborate methods to identify non-representative historical data that should not be part of the training set. We should also investigate mechanisms that put more weight on recent observations such as what is proposed for the estimation of trend component. Second, while we did incorporate one supply feature in the analysis, more research is required to establish additional evidence on which variables are needed and how they should be treated in the modelling process. In this regard, one direction would be to incorporate previously calculated elasticities factors in the model. Third, for this research, we assumed that higher hierarchies forecast can be obtained simply by summing the base forecast but other approaches need to be considered such as optimal forecast reconciliation or middle-out approach.

## Highlights

- Examines the need for medium-term forecasting in public transit systems
- Proposes an operational modelling framework to forecast ridership one year ahead at different levels of spatiotemporal aggregation
- Outlines different applications of the forecasts for tactical planning and ridership monitoring
- Exploitation of archived passive data can enhance data-driven decision making


## Author statement:

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[^0]:    ${ }^{1}$ Noted that for the subway fare transactions are linked to stations and were thus redistributed by route according to operator reporting procedure.
    ${ }^{2}$ Note that in the case of potential data loss this procedure will also result in ridership equal to zero.

[^1]:    ${ }^{3}$ Those same forecasts could also be used to schedule workforces such as field information officers or fare officers

[^2]:    ${ }^{4}$ Route C14 share a portion of C3 layout and was also impacted by road work

[^3]:    ${ }^{5}$ For $2018, N=13140=36 \times 365$

